Woods Hole Oceanographic Institution



A Passive Capture Latch for ODYSSEY-Class AUVs

by

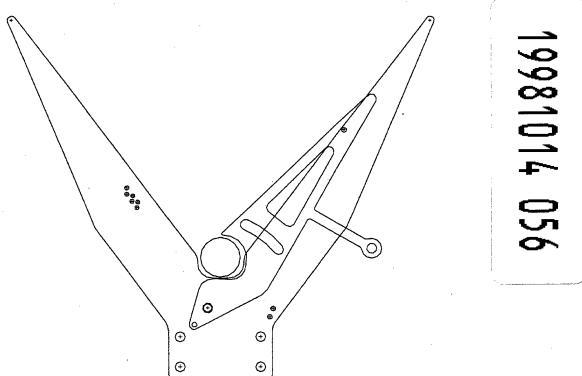
M. F. Bowen

June 12, 1998

Technical Report

Funding was provided by the Office of Naval Research under Grant No. N000-14-95-1-1316

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Dr. Timothy Stanton

Department of Applied Ocean Physics and Engineering

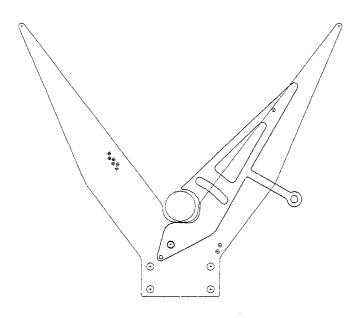
A Passive Capture Latch for ODYSSEY Class Autonomous Underwater Vehicles

Prepared By: M. F. Bowen



Version 1.0

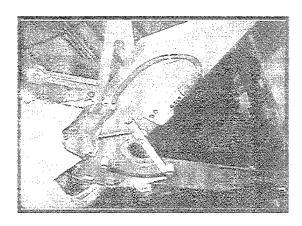
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A Passive Capture Latch for ODYSSEY Class AUVs

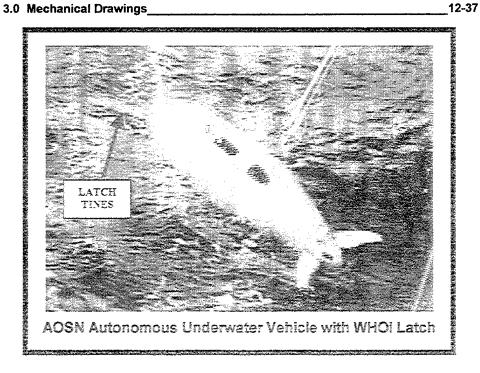
Electro-Mechanical Design,
Fabrication and Operation
for the MIT Sea Grant Autonomous
Ocean Sampling Network (AOSN)

Version 1.0



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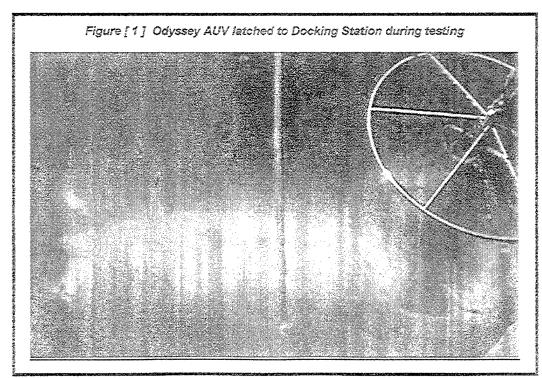


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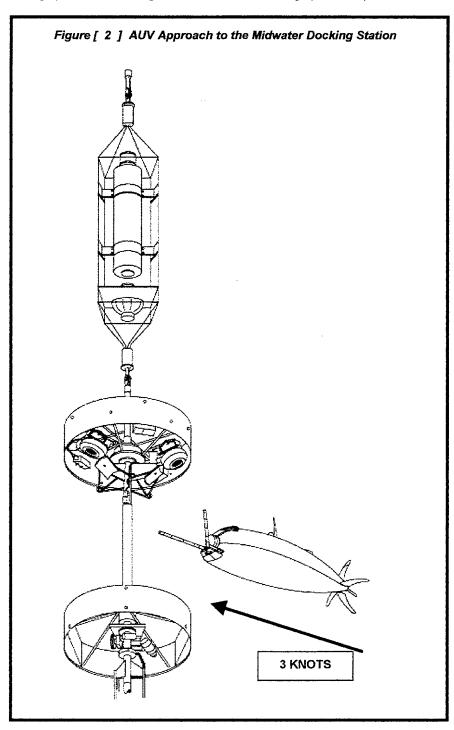
Abstract

Under subcontract to the Massachusetts Institute of Technology's (MIT) Sea Grant Autonomous Ocean Sampling Network (AOSN) program, the Woods Hole Oceanographic Institution's Deep Submergence Laboratory (WHOI-DSL) produced a passive capture latch for ODYSSEY-class autonomous underwater vehicles (AUVs). The latch is an all-titanium, split tine device, shock-mounted to the bow of the AUV. When the AUV concludes a survey mission and returns to a moored, midwater docking station, the latch leads the AUV's approach and is the first device to collide with the station's vertical docking pole. Latching to the pole is an entirely passive event requiring only forward motion of the AUV. A positive capture indication generated by proximity switches mounted on the device initiates AUV power and data transfer servicing by the station. Unlatching action requires one revolution of a latch motor cam and a brief backing command to the AUV thruster. The possibility of system malfunction was considered in latch design. If for any reason the latched vehicle cannot perform normal unlatching behavior, or the station fails, the latch defaults by securing the AUV to the moored station indefinitely. Two WHOI AUV latches have been used successfully on three offshore engineering test cruises. (195) Keywords: AUV, latch, docking.



1.0 Introduction

The MIT Sea Grant Autonomous Ocean Sampling Network required Odyssey-class AUVs to navigate toward and couple with a midwater docking station suspended by a deep sea mooring system. The AUV, on a pre-programmed survey mission, would terminate its mission by homing in on a mooring beacon and collide with the target, a vertical stainless steel pole comprising the center of the docking station (Figures [1 and 2]). The AUV travels in the horizontal plane at a nominal speed of three knots (1.2 m/sec). A heavy-duty titanium latch was produced by WHOI that could withstand the 1G+ impact with the semi-rigid pole reliably under a wide range of approach conditions. The latch was also capable of retaining the vehicle during a variety of servicing operations, mooring translations and undocking operations prior to a new mission.



2.0 AUV Docking Latch

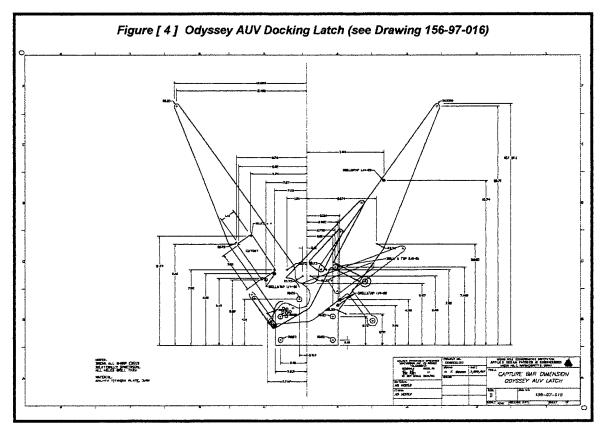
2.1 Background and Theory of Operation

The latch specification has gone through several iterations in three years, see Figure [3] below.

Prototype Latch Design	Advantages	<u>Disadvantages</u>
1) retractable body, hinged tines, detent trigger	hydrodynamic	mechanical complexity
2) fixed body, hinged tines, stiff spring trigger	positive capture	software dependencies
fixed body, fixed tines, passive latching, solenoid release	simplicity	high power consumption, poor hydrodynamics
fixed body, fixed tines, passive latching, motor and cam release	simplicity	hydrodynamics

The current latch mechanism is shown in plan view in Figure [4] and a photograph of the latch appears in Figure [5]. The latch consists of: a vee-shaped, symmetrical grade 2 titanium body with two fixed tines; a pivoting titanium (pole) capture bar; a titanium capture bar guide; a titanium mount with shock absorption; an isolated stainless steel extension spring; a drive motor with housing, cam and linkage; four pressure-proof magnetic proximity switches; and four magnets.

The latch specification appears in Figure [9]. In the early stages of design, MIT hydrodynamicists were concerned that the "wing-like" shape of the latch would degrade control performance of the vehicle, particularly in pitch. Field operations of the completed design proved that the latch's influence on control was negligible.



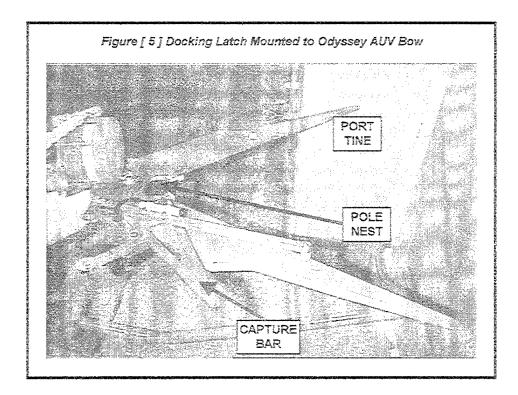
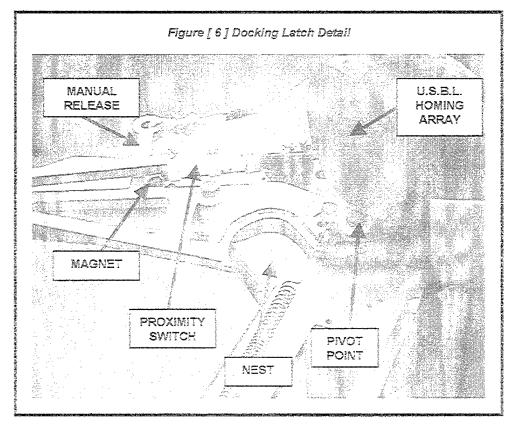
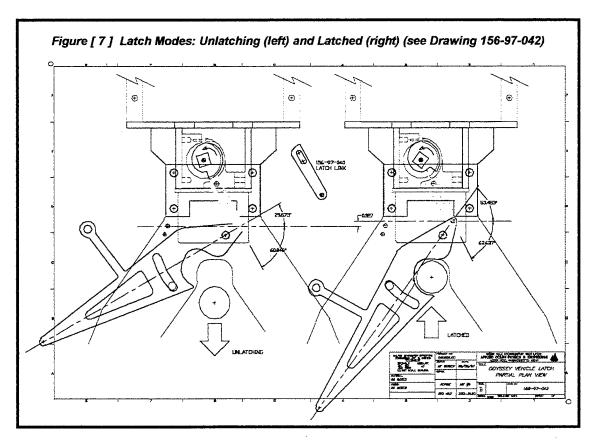
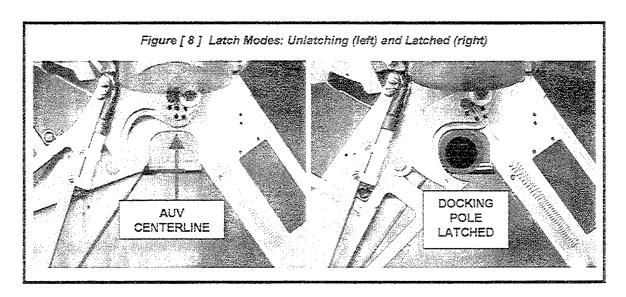


Figure [6] shows a close-up of the latch nest area. Mounted just below and forward of the ultrashort baseline homing array, the latch prohibits the docking pole collision from damaging the brow of the AUV. A manual release loop on the capture bar allows undocking from the docking pole during testing. The wedge-like shape of the capture bar aids in positive latching in "second-bounce" and low-speed docking circumstances.





The docking pole enters the latch anywhere between the two fixed tines of the latch body, which are spaced twenty-four inches apart at the forward tips. The tines are angled and direct the pole toward the AUV centerline, taking advantage of the forward motion of the AUV and the relative mobility of the pole. The pole then pushes the capture bar aside and enters a nest in the latch body, where an extension spring closes the capture bar around the pole. The AUV may latch onto the pole anywhere within a one and one half-meter vertical length. When latched (Figure [7 right]), the AUV must remain safely mated to the pole by the latch alone, either temporarily as part of a mission servicing, or indefinitely as the result of an unsuccessful deployment (such as a dock and mooring recovery with the AUV still attached). To unlatch (Figure [7 left]), the motor rotates a cam one revolution and briefly opens the capture bar, allowing the pole to escape the latch nest. Figure [8] below demonstrates the same modes as built.



2.2 Latch Specification Figure [9]

MECHANICAL

ACCEPTANCE GAP

DESIGN, FUNCTIONAL

DESIGN. SHAPE

24 IN

PASSIVE LATCHING

FIXED, VEE-SHAPED TINES

BI-LATERALLY SYMMETRICAL

ACTIVE UNLATCHING

FORCE OF IMPACT

GEARHEAD REDUCTION

</=1.0 VEHICLE G (600 LBS. MASS) 1525.7:1

2 LBS. OR </= 75% BOLLARD THRUST (11 LBS. REF)

(MAXON PLANETARY GP032A057-1526E1A01A) LATCH, SPEED RANGE 0.3 TO 3.0 KNOTS

LATCH, SPRING FORCE

LENGTH, MOTOR & CAM

LENGTH, TINE TO USBL LENGTH, TINE TO SHOCK MOUNT

MATERIALS

7.5 IN VERTICAL 19.5 IN HORIZONTAL

25.0 IN HORIZONTAL

GRADE 2 TITANIUM (SG 4.52)

316 STAINLESS (SG 8.03)

DELRIN (SG 1.43) NYLON (SG 1.15)

MOVING PARTS, ACTIVE MODE

MOTOR SHAFT CAPTURE BAR **EXTENSION SPRING**

MOVING PARTS, PASSIVE MODE

CAPTURE BAR **EXTENSION SPRING**

OUTSIDE DIAMETER, MOTOR UNLATCH, FOLLOWER FORCE

UNLATCH, FOLLOWER THROW WEIGHT AIR, BODY ASSY WEIGHT AIR, MOTOR ASSY

WEIGHT AIR, TOTAL WEIGHT SEAWATER, TOTAL 2.25 IN >/= 18 LBS. 0.5 IN

3.5 LBS. (1.59 KG) 22.1 LBS. (10.04 KG) 13.0 LBS. (5.91 KG)

18.6 LBS. (8.45 KG)

ELECTRICAL

CONDUCTORS

CONNECTORS

CONSUMPTION, CURRENT CONSUMPTION, POWER

CONSUMPTION, VOLTAGE

MAGNETICS

RPM, MOTOR

RPM, CAM SHAFT

SENSING, CAM FOLLOWER

SENSING, LATCHING SENSING, UNLATCHING SENSING, CAPTURE BAR TORQUE, CAM SHAFT

2 IE XSA-BC, 2 IE RMA-FS 147 MA

0.76 WATTS 12 VDC NOMINAL (RANGE 5-18 VDC)

UNMEASURED (MINIMAL)

4790 (MAXON RE025-055-37EAA200A) 2.0

MOVEMENT DETECT MAG SWITCH (N.O.) "POLE PRESENT" MAG SWITCHES (N.O.) "POLE ABSENT" MAG SWITCH (N.O.) MOVEMENT DETECT MAG SWITCH (N.O.)

500 OZ-IN

ENVIRONMENTAL

CAM FUNCTION, READY FOR POLE 90 DEG, 7.5 SEC CAM FUNCTION, RELEASING POLE CAM FUNCTION, LATCH OPEN

DEPTH RATING

DUTY CYCLE MTBF

RETENTION, MAX PITCH RETENTION, POWER LOSS

RETENTION, MAX ROLL TEMPERATURE, OPERATING TEMPERATURE, STORED

180 DEG, 15.0 SEC 90 DEG, 7.5 SEC

2000 METERS (3000 PSI)

20 LATCHING COLLISIONS PER DEPLOYMENT

4 MONTH IMMERSION

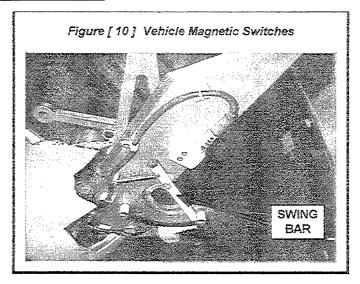
15 DEG UPCURRENT, 10 DEG DOWNCURRENT

NO UNLATCH FUNCTION

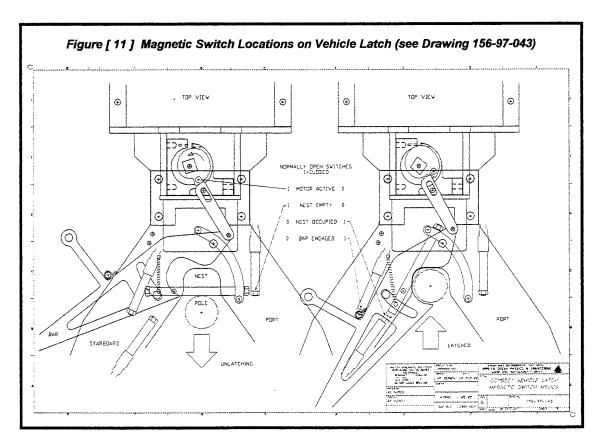
+/- 15 DEG -15C TO 80C

-40C TO 80C

2.3 Magnetic Switch Harness



A portion of the vehicle magnetic switch harness appears in a picture taken from below a latch in Figure [10]. The location of the four switches and four matching magnets appears in Figure [11]. The function of these sensors is to indicate to the vehicle, and its behavior software, exactly what state the latch is in at any time during servicing at the Docking Station or between missions away from the Station. One magnet indicates the state of the motor, which can open the capture bar. Another switch indicates whether the capture bar is open or closed. Two switches are located at either end of a plastic swing bar. One indicates if the bar has been moved away from the nest and a pole is present (docked and latched). A second indicates whether the swing bar has sprung across the pole nest whenever the latch is off the pole (undocked and pole absent).



2.4 Performance Analysis

There are two working latches mounted onto Odyssey AUVs at the writing of this report. One of the two has been field tested prior to this cruise and has successfully latched and unlatched from a docking pole more than fifty cycles. Both latches have been wet tested with vehicles and a docking pole under controlled circumstances at WHOI. During this cruise to the Labrador Sea the latch capture bar was disabled for all missions to the Docking Station.

During this cruise one magnetic switch harness failed once due to seawater intrusion and was replaced by a spare harness.

2.5 Proposed Improvements and Modifications

2.5.1 Latch

This fixed-tine latching device will probably not change significantly in the short-term nor for the duration of the AOSN project. As the fourth revision of the original specification, this design has proven to be easily maintained, functional, immune to prolonged immersion, robust and reliable.

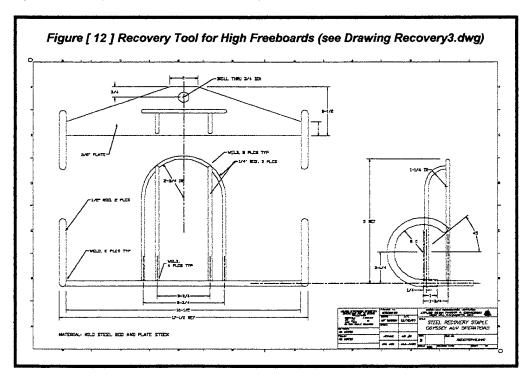
2.5.2 Specialized Recovery Device

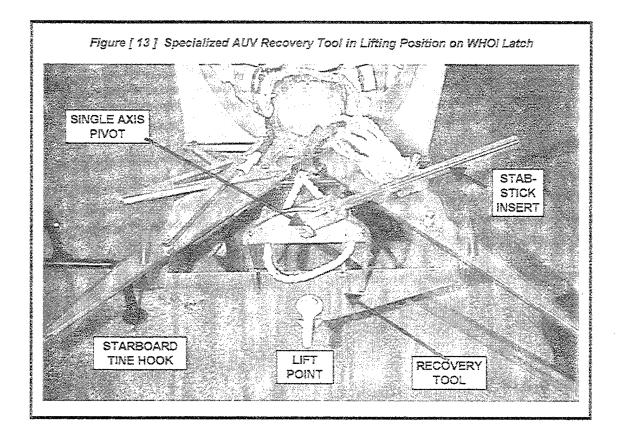
The inherent strength of the titanium latch and bow mount was demonstrated by accident during the October engineering test cruise when the lifting bail on a deployed vehicle parted. A lifting hook and line was attached to the port latch tine and the AUV was retrieved vertically without further damage.

In response to this emergency scenario, a custom recovery tool was designed by WHOI and two were fabricated. The device is shown in Figures [12] and [13]. Known as the "staple", it can be hung over the ship's side at the end of a long stab stick and jammed into the latch where two hooks engage the outboard edge of the latch tines. The vehicle can then be safely lifted vertically out of the water by the tines in situations of high freeboard and high seastates. The staple has not been tested offshore to date.

2.5.3 Acoustically Active Latch Tines

A recommendation has been made for the long-term that the two outer tine tips be hollowed out and fitted with a revised version of the homing head elements. This scheme would give the piezo array the advantage of a wide separation, and the mechanical protection of a metal shell.



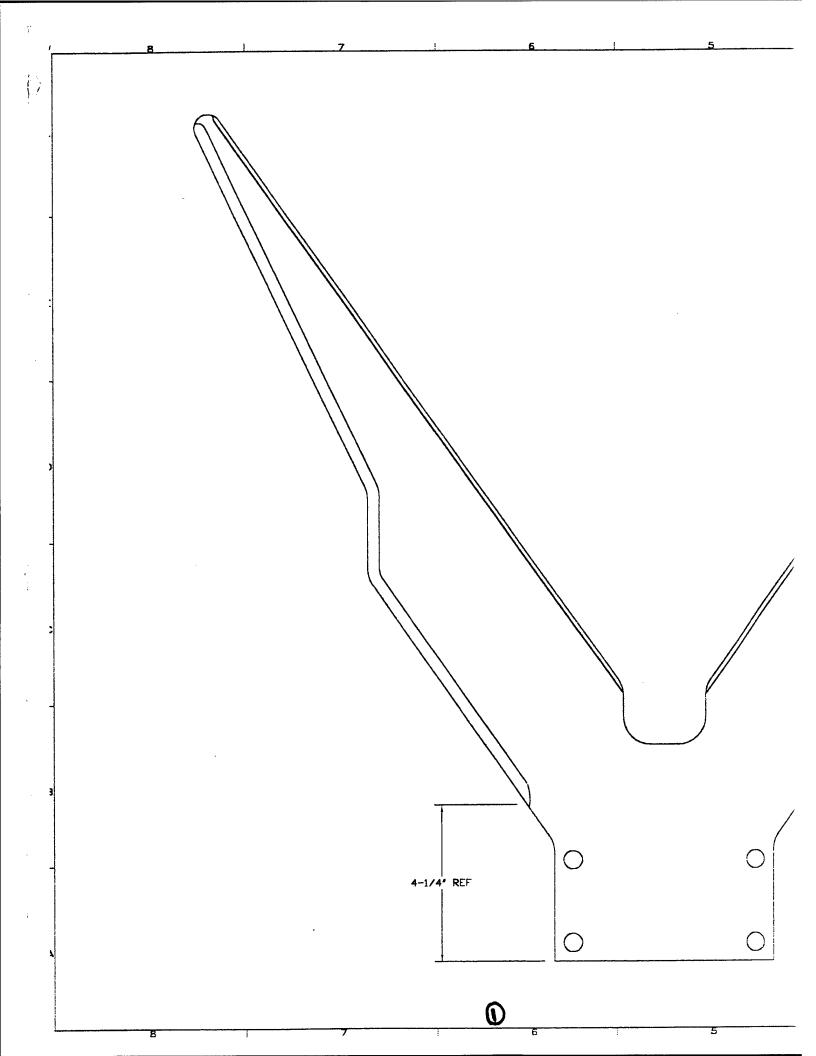


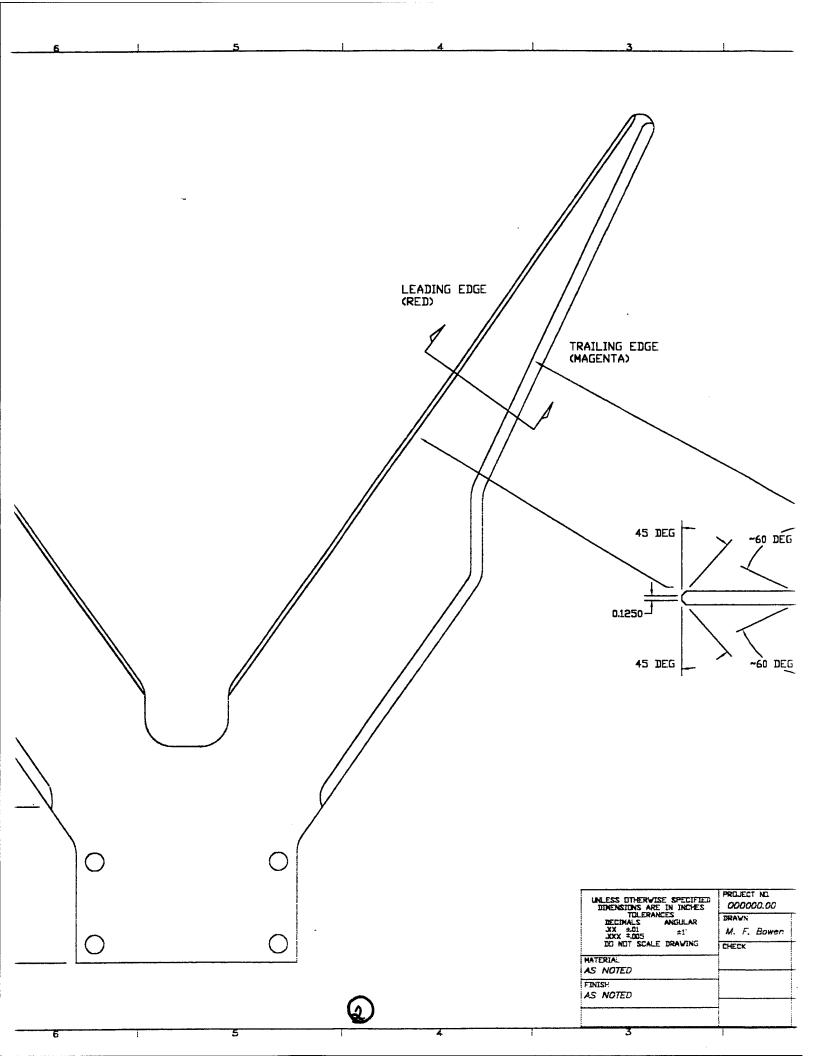
2.6 References

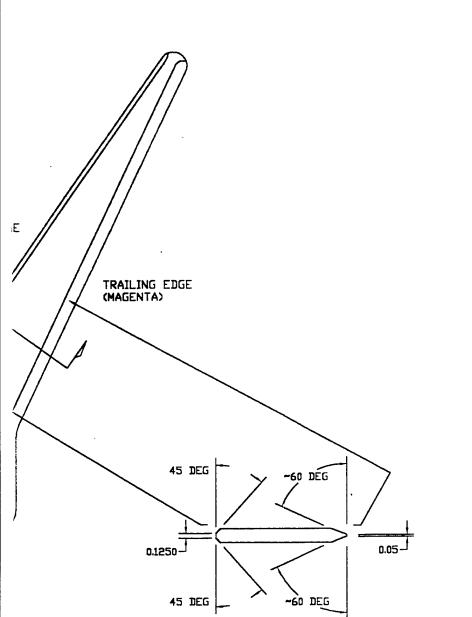
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- Currey, N.S., <u>Aircraft Landing Gear Design: Principles and Practices</u>, Lockheed Aeronautical Systems Company, AlAA Educational Series, Air Force Institute of Technology, Wright-Patterson Air Force Base, Ohio, American Institute of Aeronautics and Astronautics, Inc., Washington, D.C. 20024, ISBN 0930403-41-X, 1988.
- Currey N.S., <u>Landing Gear Design Handbook</u>, Lockheed-Georgia Company, A Division of Lockheed Corp., Marietta, GA 30063, 1st Edition, January 1982.
- 5. Dexter, S.C., <u>Handbook Of Oceanographic Engineering Materials</u>, Robert E. Krieger Publishing Company, Malabar, Florida, 1985.

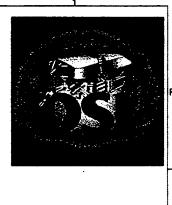
MECHANICAL DRAWINGS

<u>LA I</u>	CH BODY		
	156-97-005	MILLING MOD, BODY CHAMFER	13
	156-97-010	BAR GUIDE AND STANDOF	14
	156-97-025	BAR GUIDE AND STANDOF TITANIUM STOCK CUTOUT PATTERN	15
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	156-97-035	CAM, MOTOR	34
	156-97-040	LINK, MOTOR	35
		MOUNT, MOTOR TRANSFER PLATE, MOTOR	36 37
	156-97-043	IKANOFEK PLATE, WUTUK	3 <i>/</i>



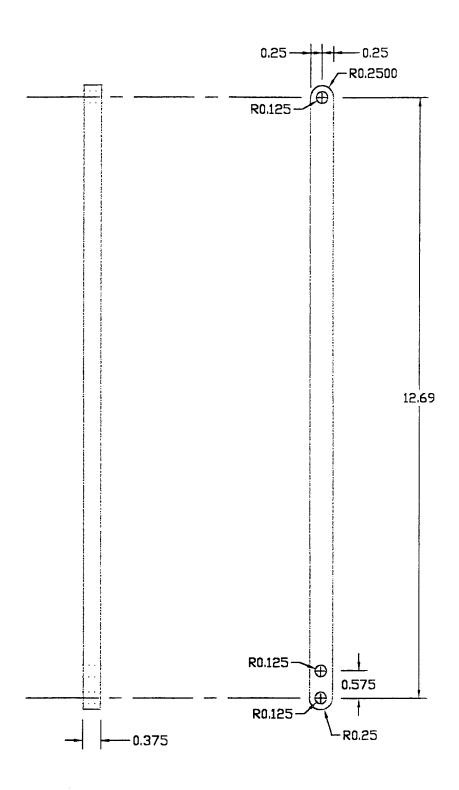






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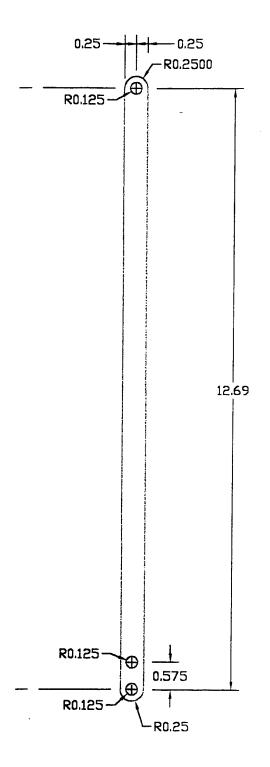


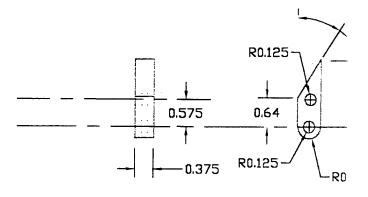


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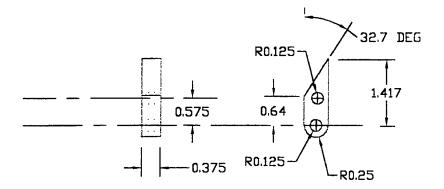






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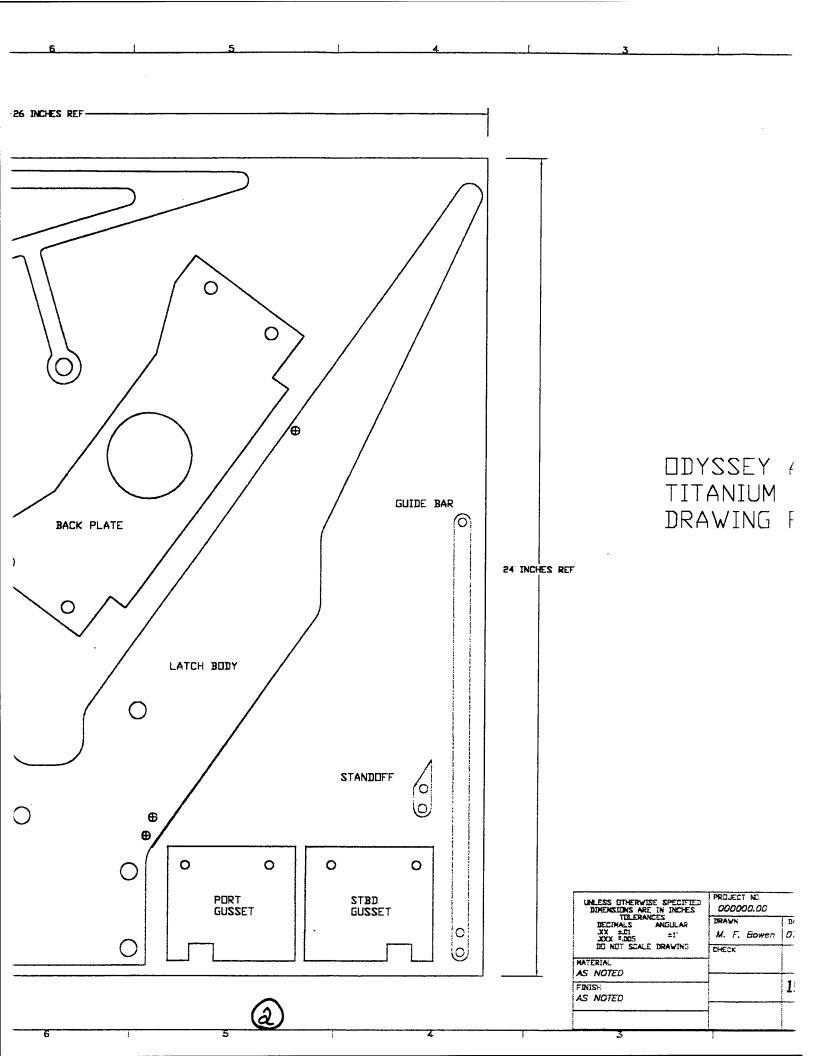
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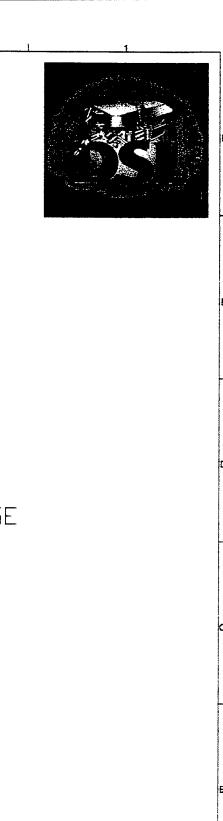


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-26 INCHES REF-CAPTURE BAR 3/8' TITANIUM PLATE STOCK PROVIDE ON ACCT. 156168.08 MF BOWEN, X3420 BACK PLATE LATCH BODY BOTTOM PLATE € ₩ 0 0 PORT GUSSET





ODYSSEY AUV TITANIUM LATCH DRAWING PACKAGE

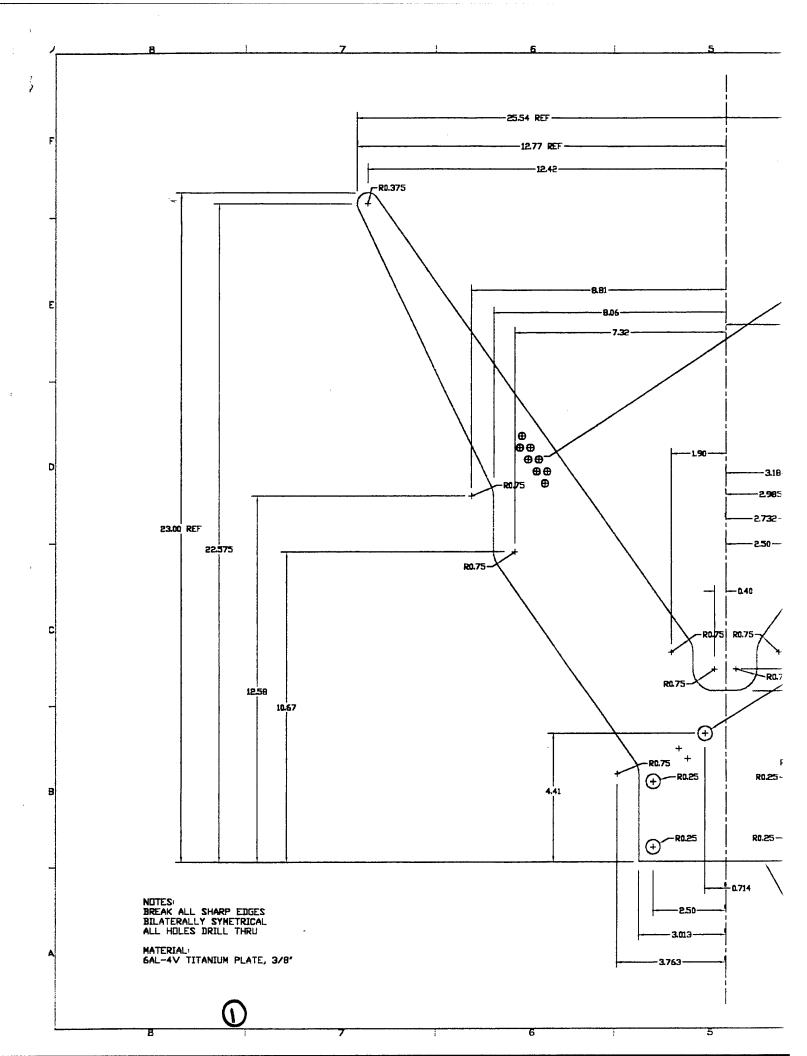
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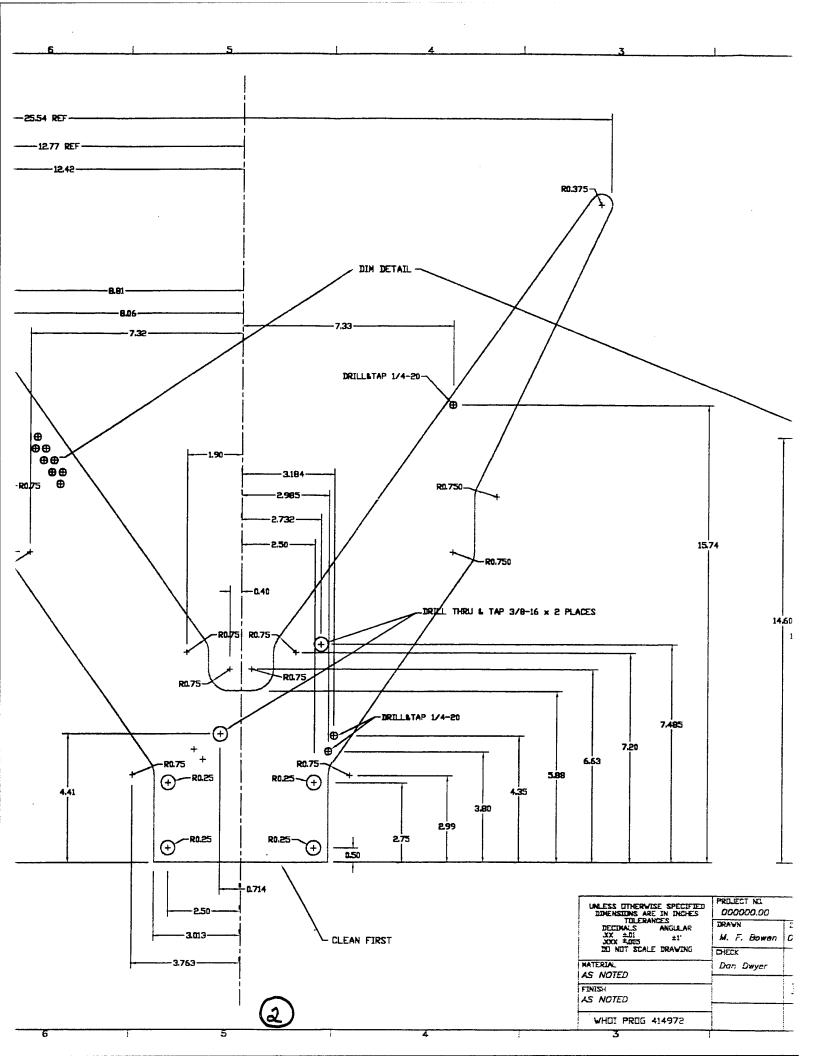
BAR

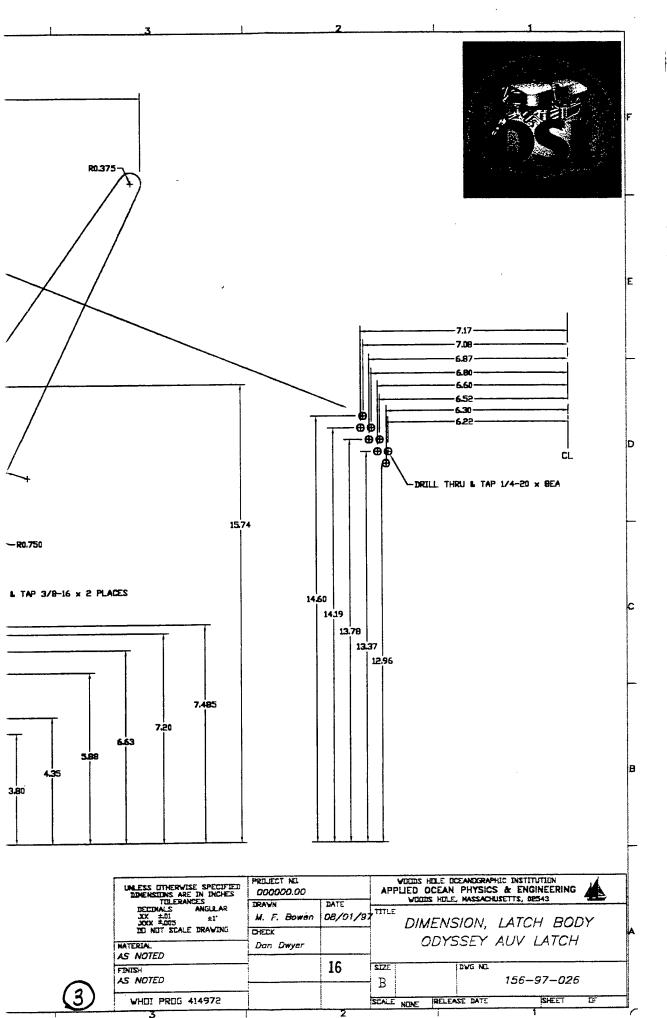
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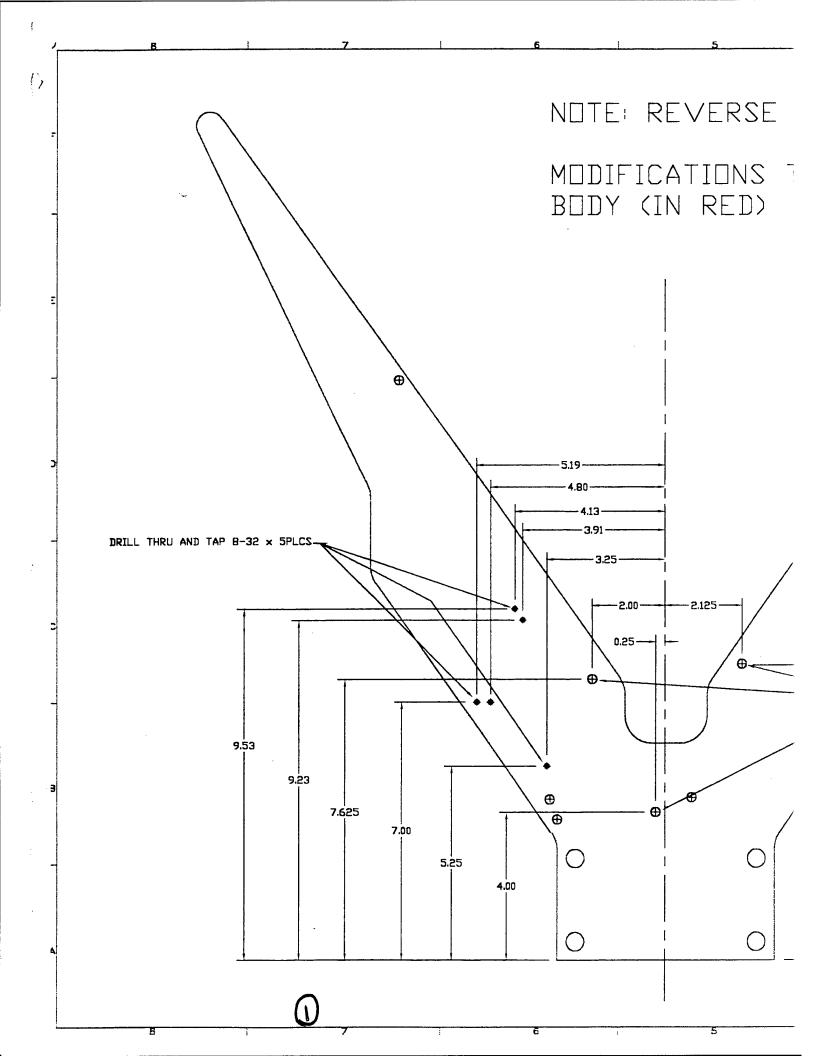
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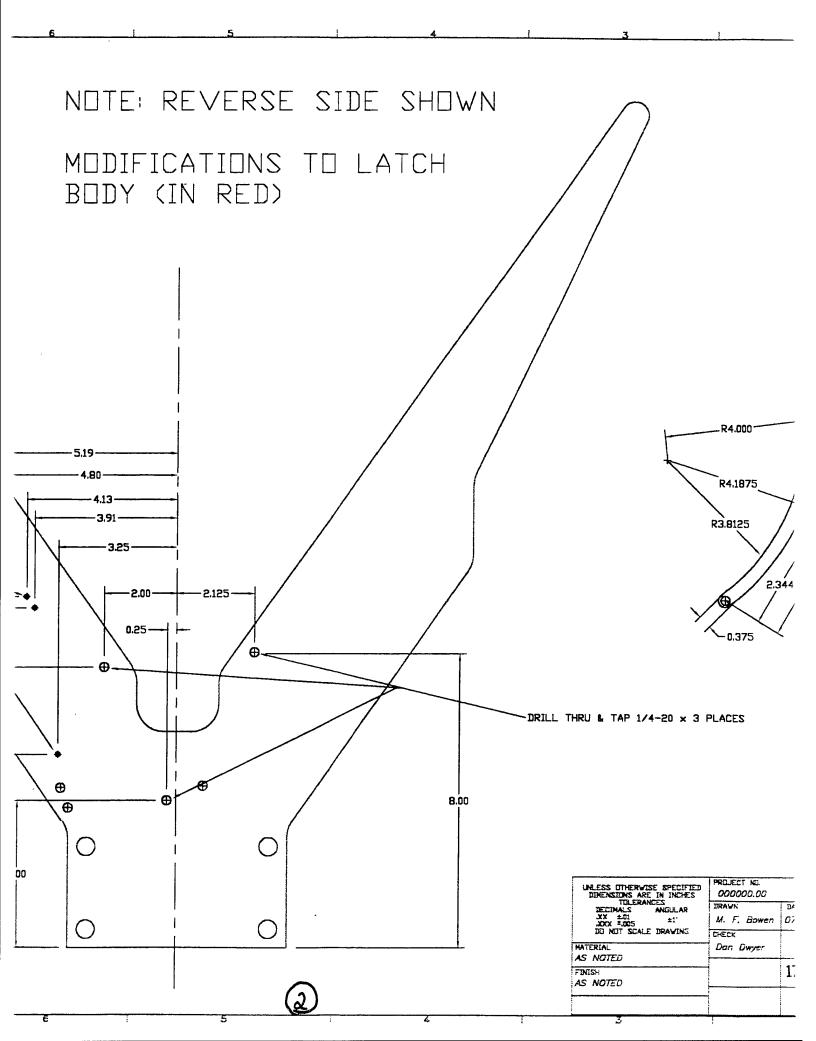
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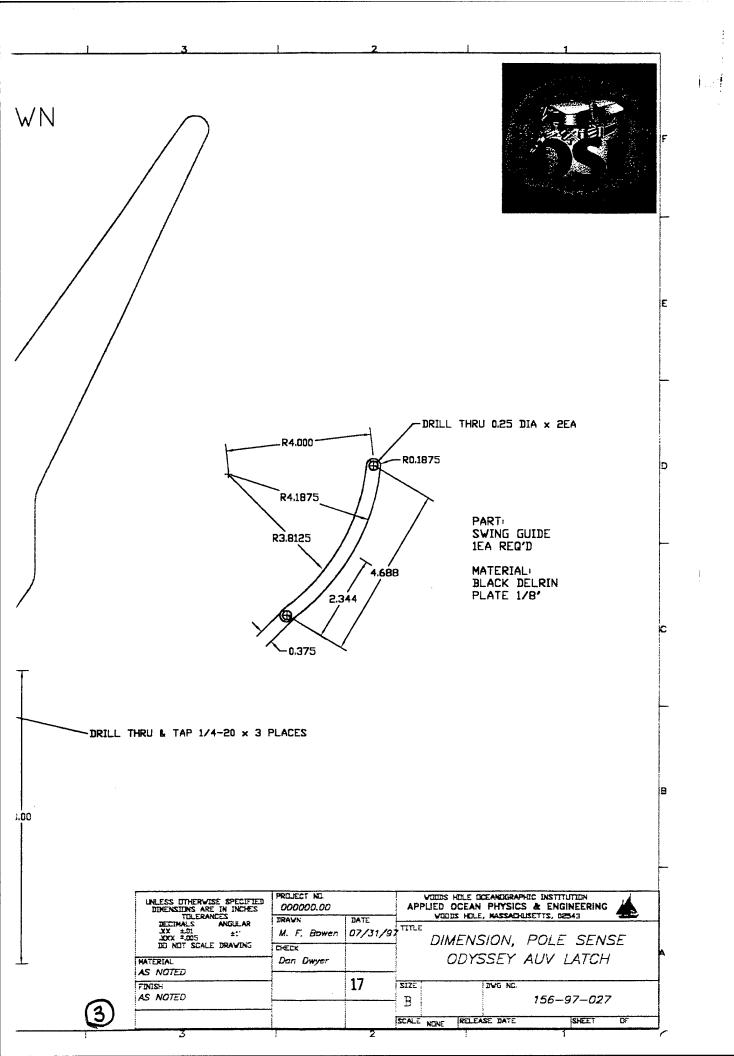


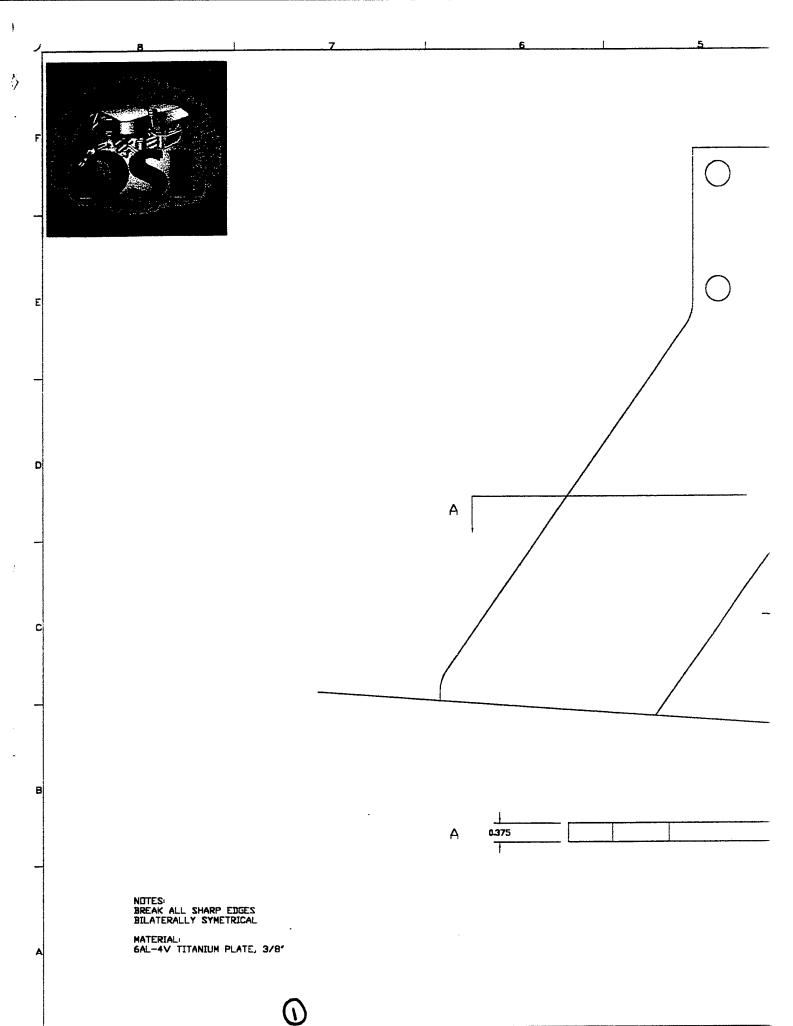


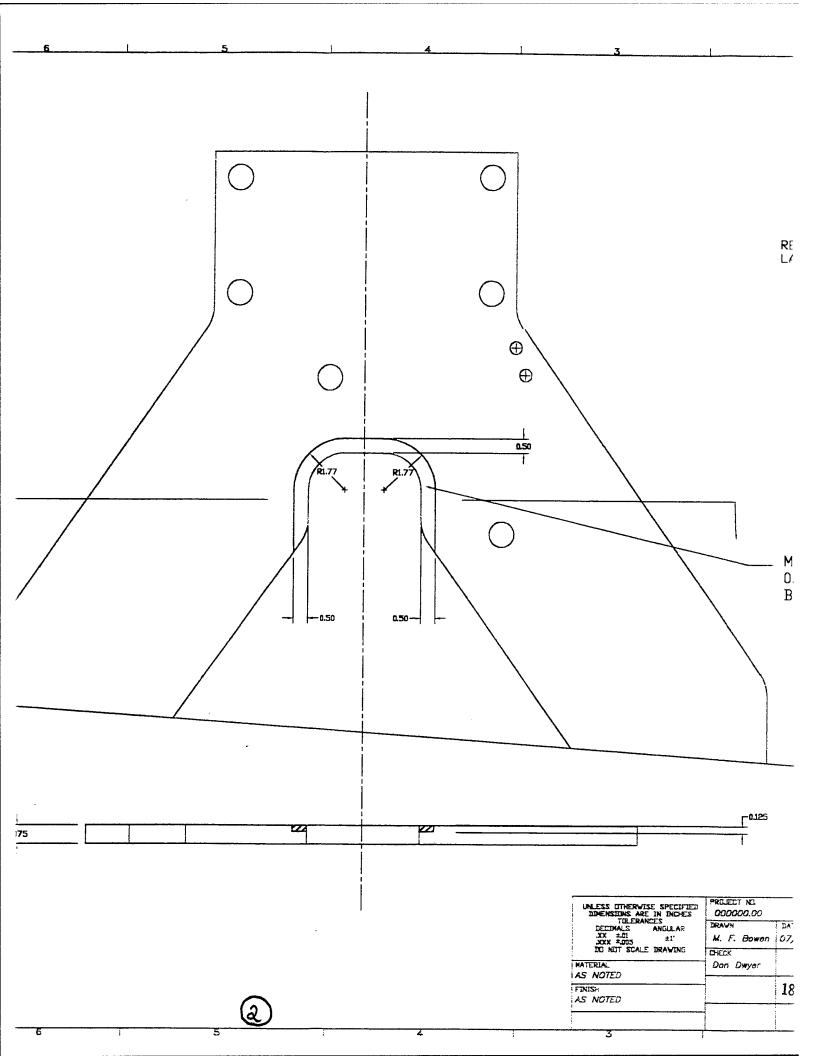


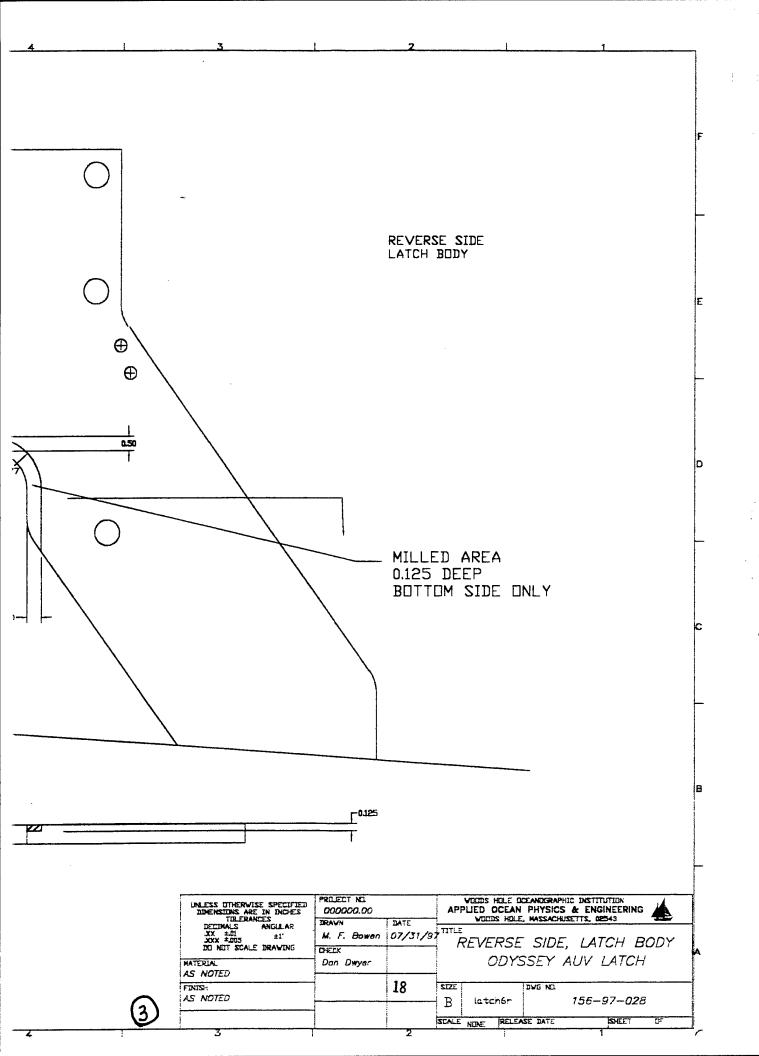


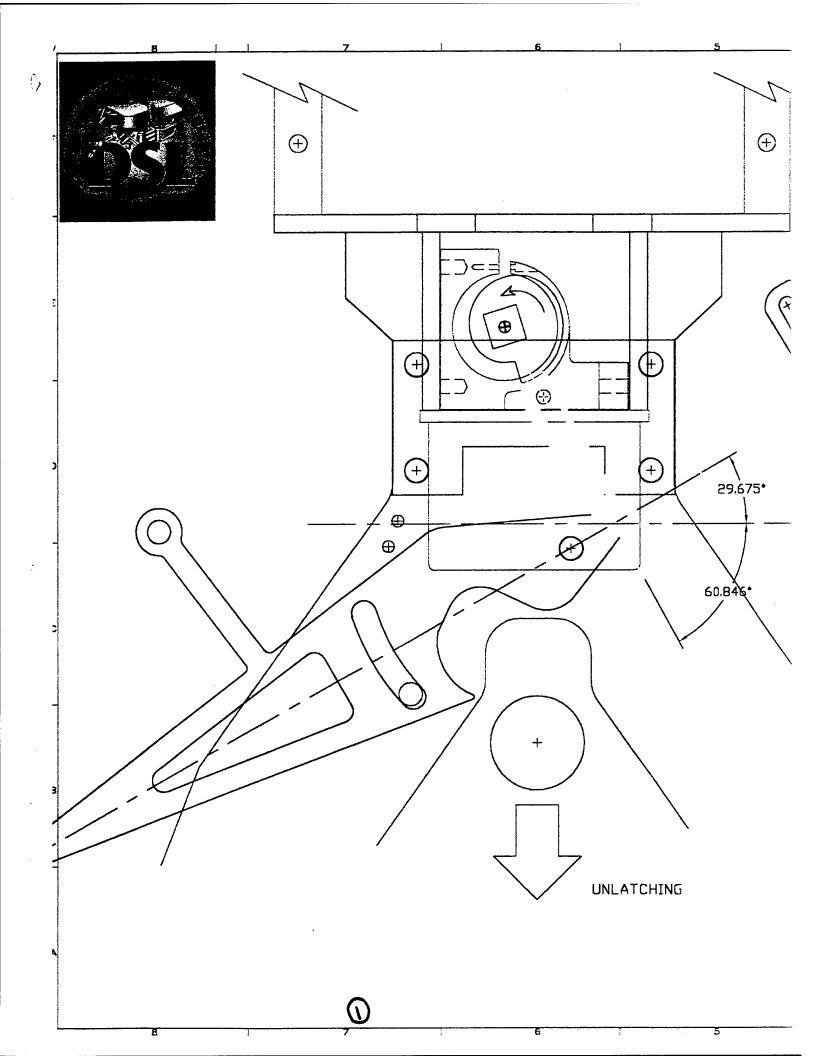


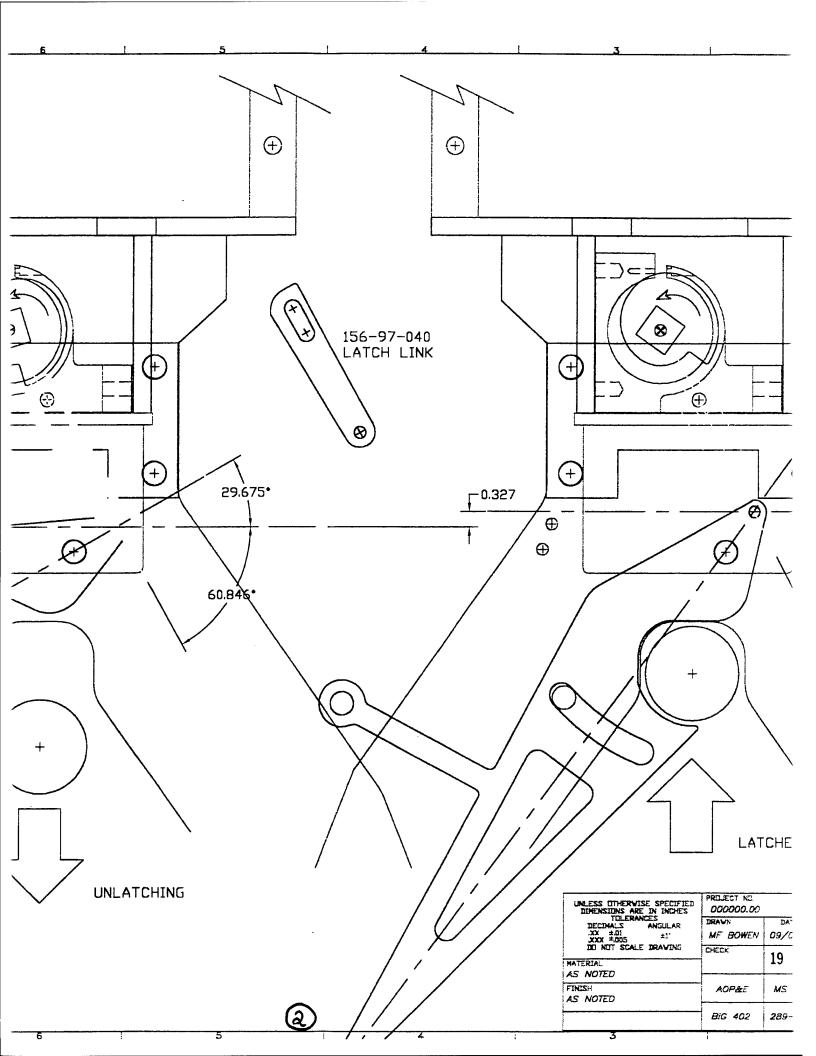


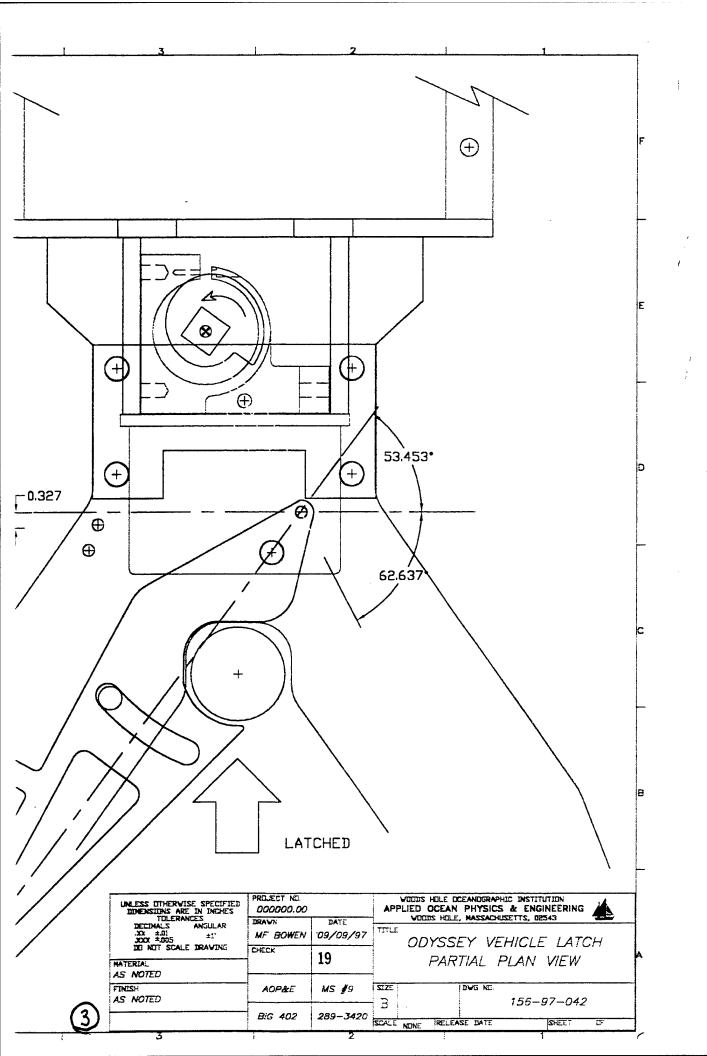




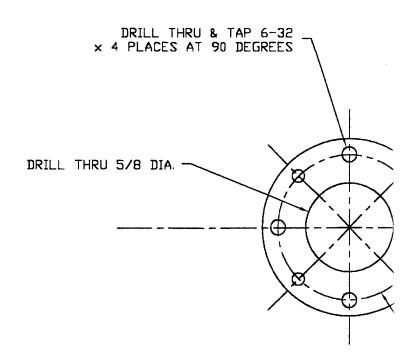






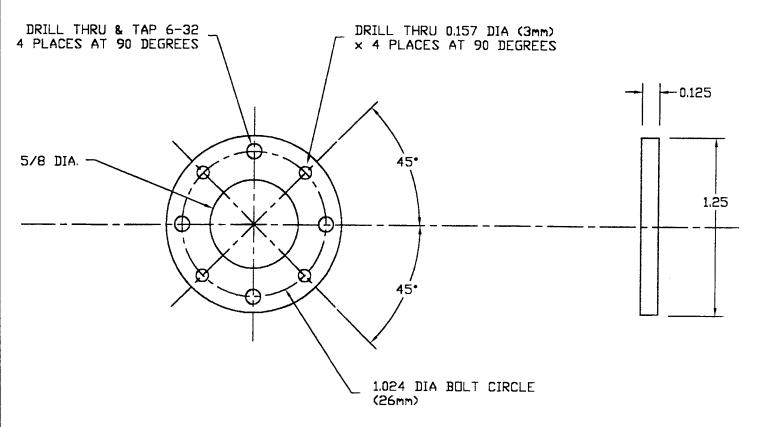






NOTES:
MATERIAL IS 6061-T6 ALUMINUM
PLEASE BREAK SHARP EDGES
2EA REQ'D
MARTIN BOWEN
(508) 289-3420 WHOI
(508) 457-2132 FAX

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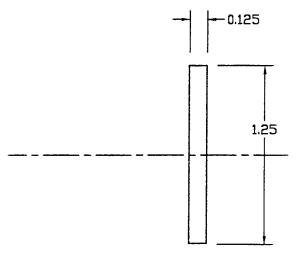
ES: ERIAL IS 6061-T6 ALUMINUM ASE BREAK SHARP EDGES REQ'D TIN BOWEN) 289-3420 WHOI) 457-2132 FAX

		UNLESS DITHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TOLERANCES
	*	DECIHALS ANGULAR

PROJECT NO. 000000.00 DRAVN MF BOWEN XX ±.01 ±1'
XXX =.005
DD NOT SCALE DRAVING 09/1 CHECK 20 MATERIAL AS NOTED FINISH AOP&E MS AS NOTED BIG 402 **28**9-

(2)

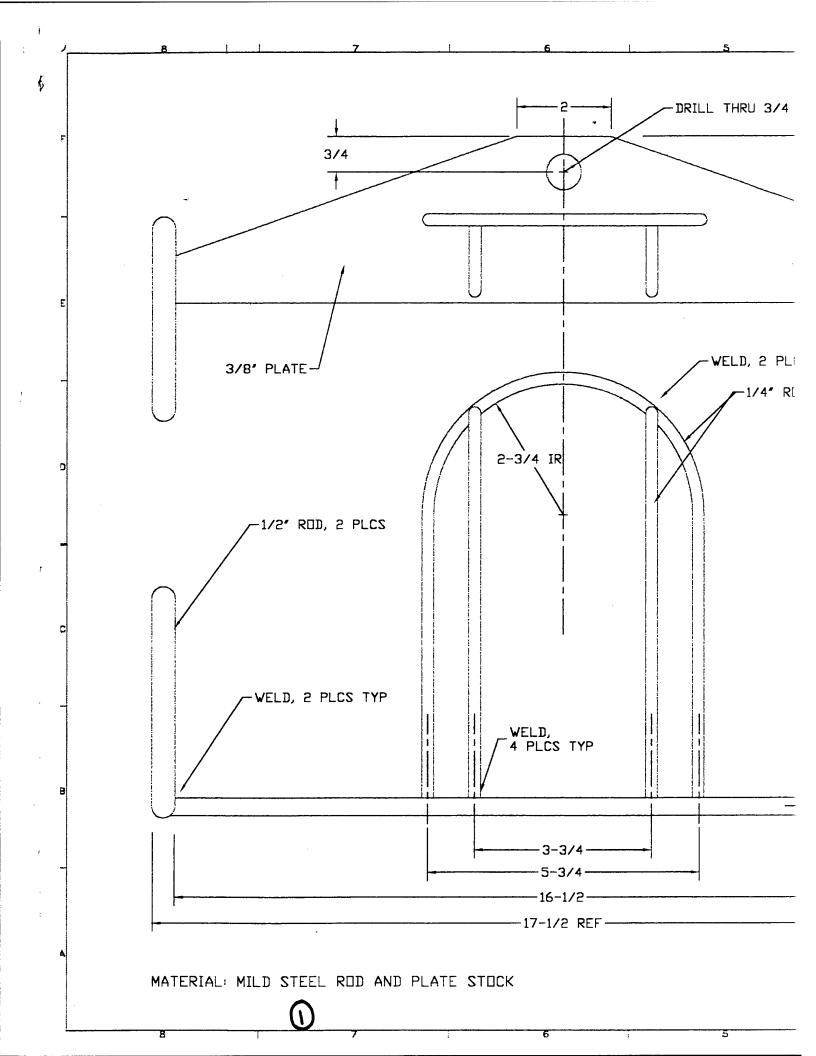
57 DIA (3mm) T 90 DEGREES

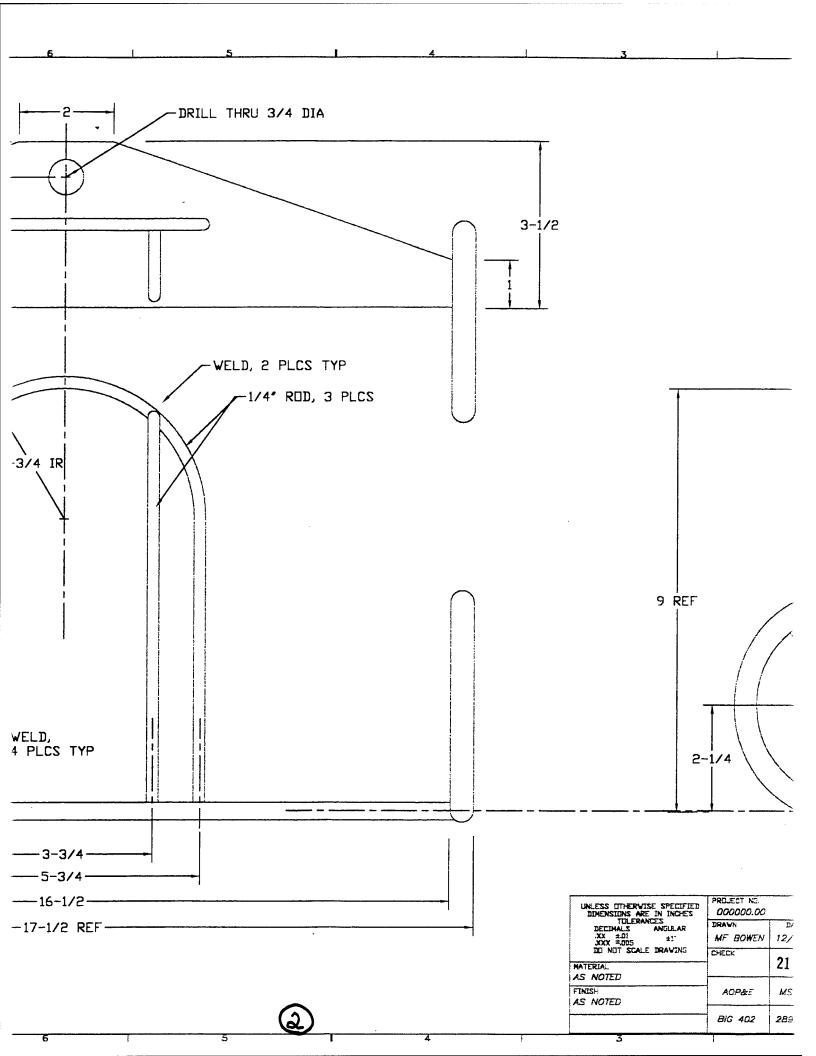


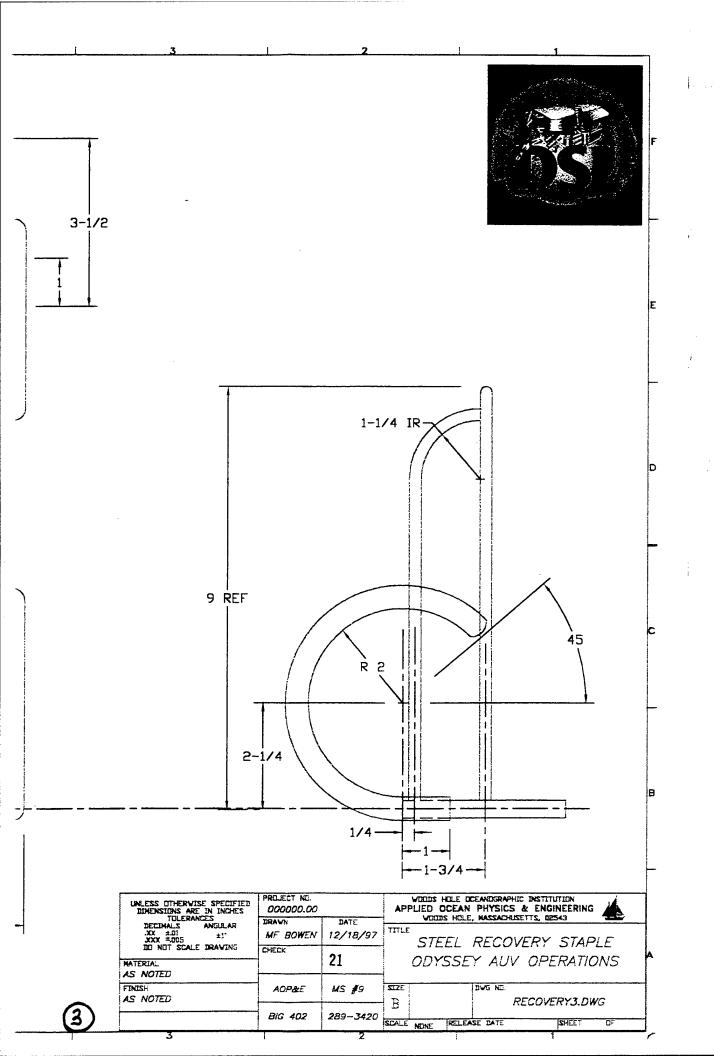
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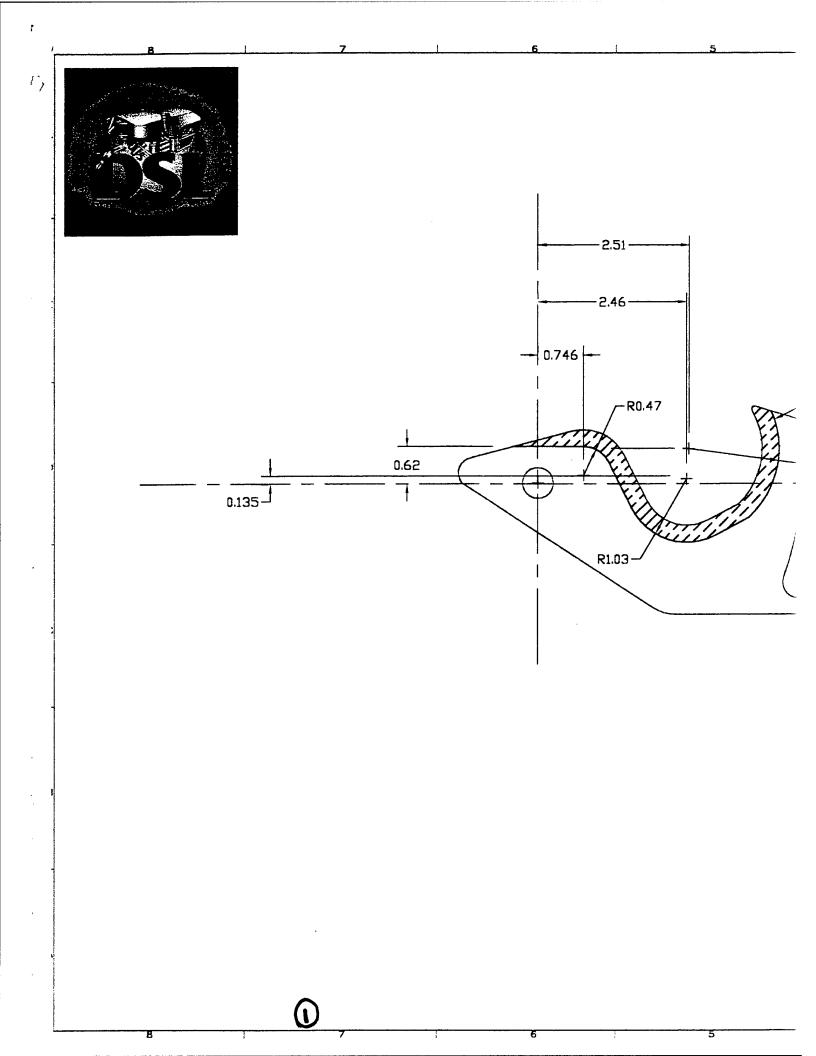
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	PROJECT NO. 000000.00		APPLIED OCEAN PHYSICS & ENGINEERING	
TOLERANCES DECIMALS ANGULAR .XX ±.01 ±1 .XXX ±.005	MF BOWEN	DATE 09/12/97	TITLE TRANSFFR PLATF	
IN NIT SCALE IRAVING MATERIAL AS NOTED	CHECK	20	ODYSSEY LATCH MOTOR	
FINISH AS NOTED	AOP&E	MS ∦9	SIZE DWS NO. R 1.56-97-04.3	
	BIG 402	289-3420	SCALE 3 1 RELEASE DATE SHEET OF	

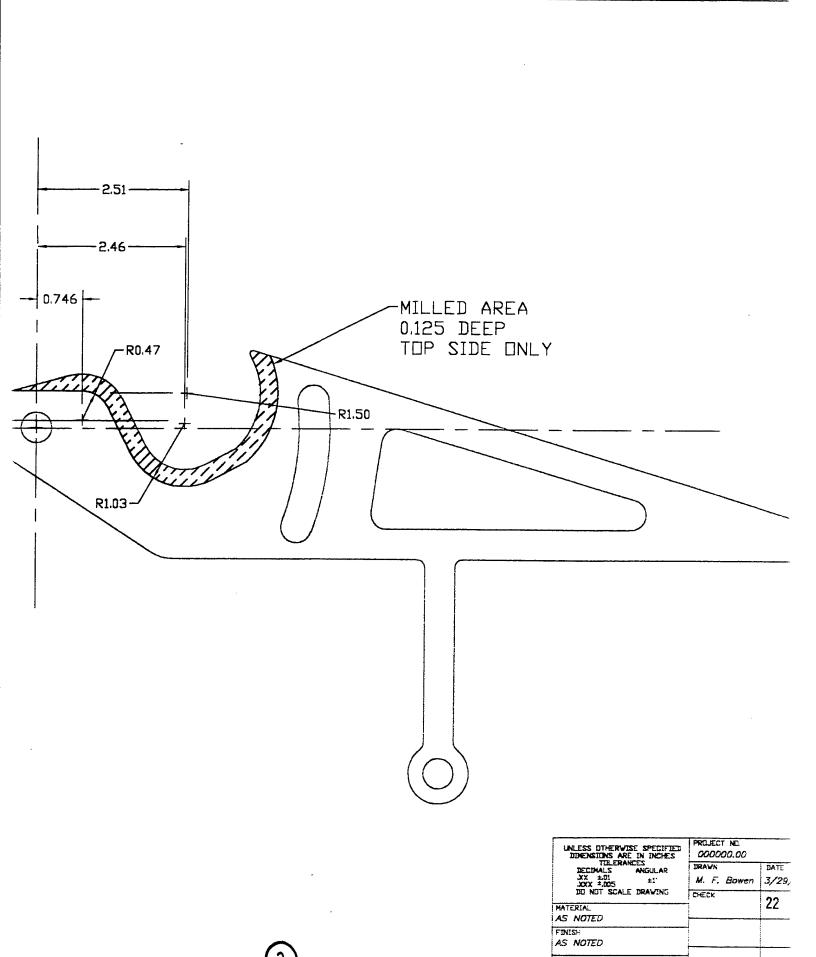
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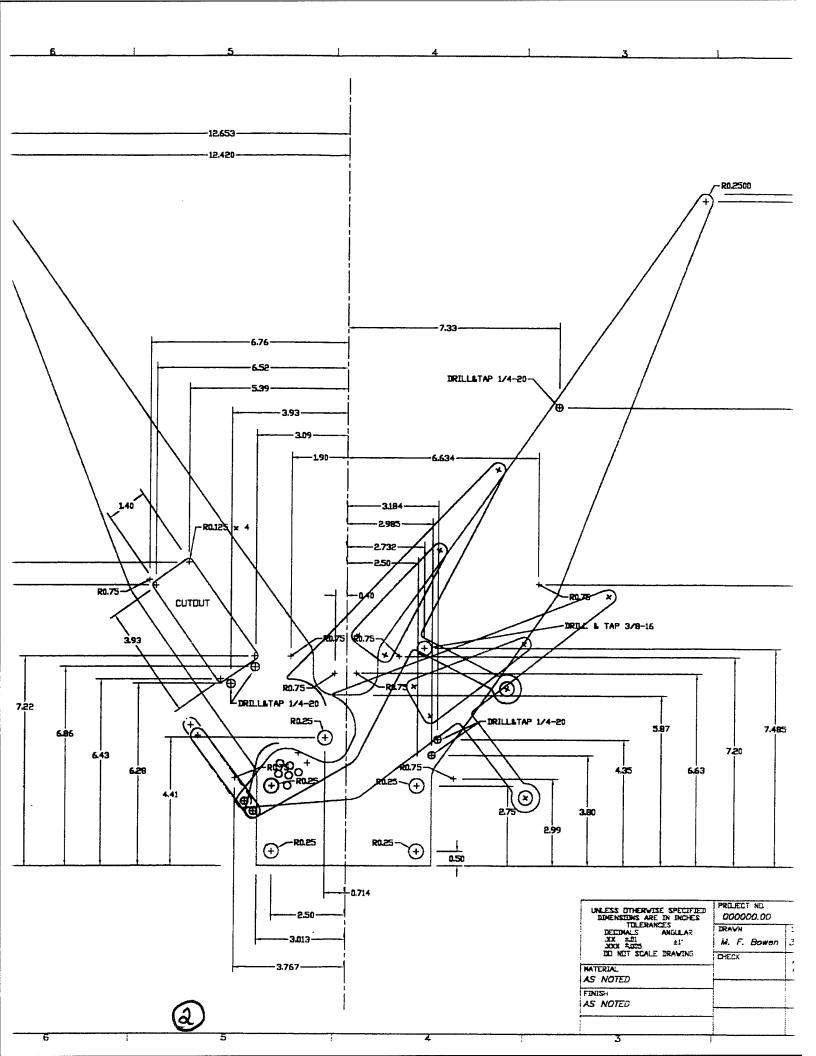


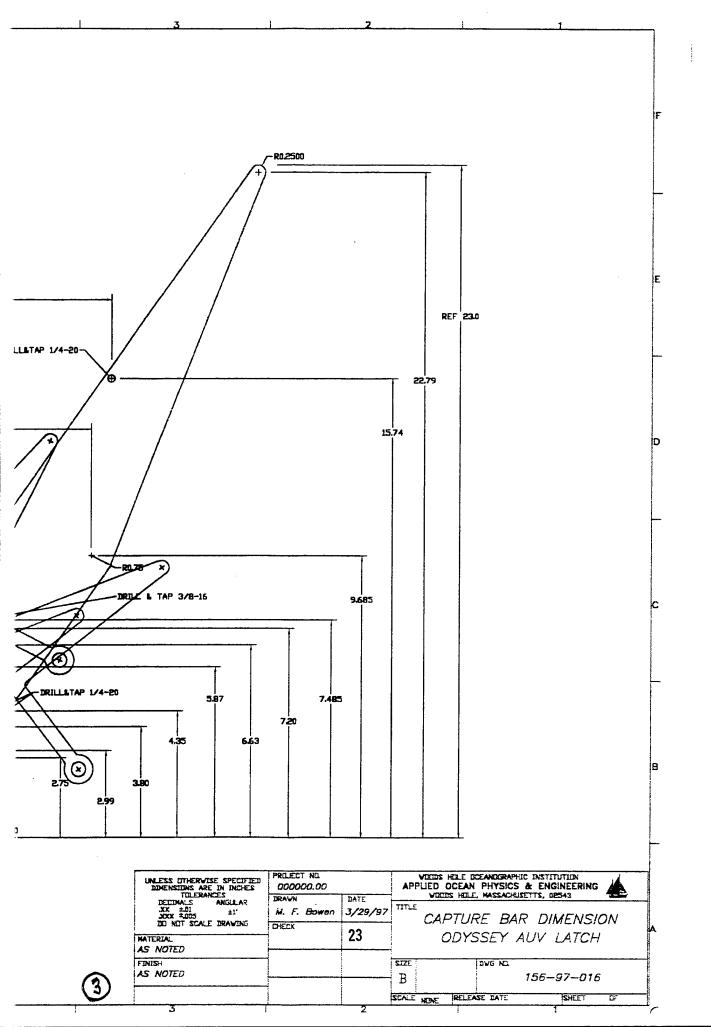
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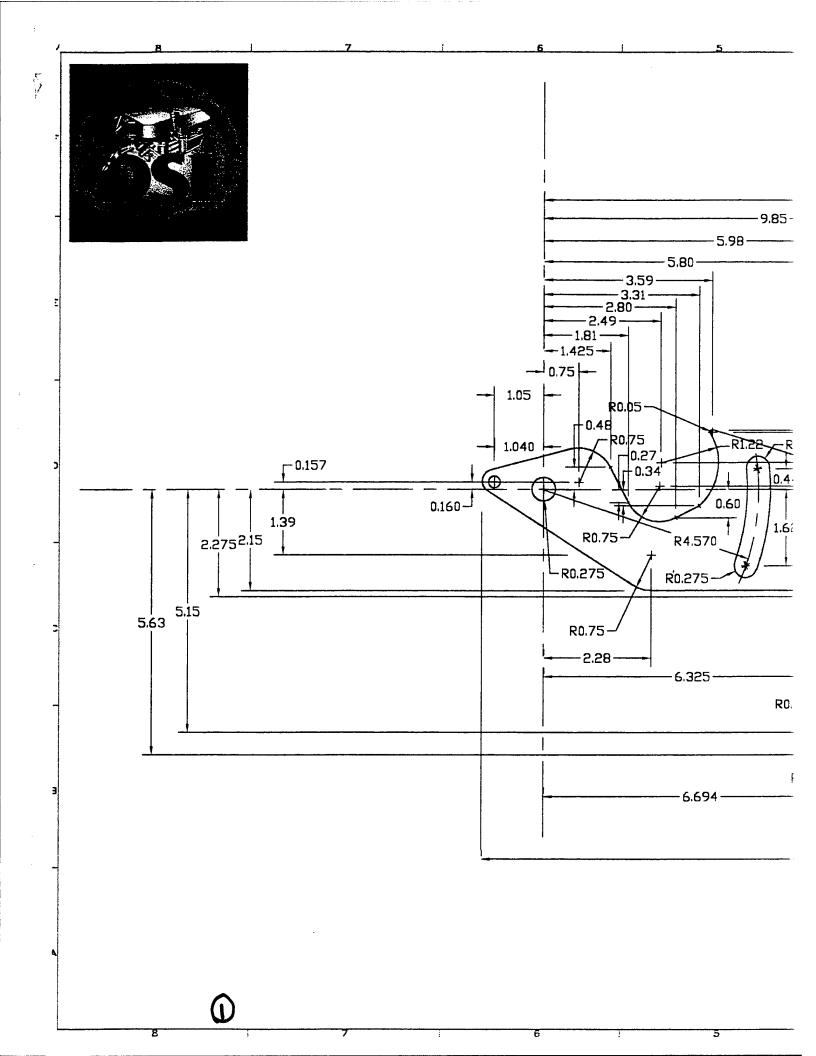
	UNLESS OTHERWISE SPECIFIED DIRENSIONS ARE IN INCHES	PROJECT NO. 0000000.00		APPLIED OCEAN PHYSICS & ENGINEERING			
	TELERANCES BECHALS ANGULAR XX ±01 .X0X ±005 ±1 BEL NOT SCALE DRAVING HATERIAL AS NOTED	M. F. Bowen	DATE en 3/29/97	TITLE			
		CHECK	22	MILL MOD, LATCH CAPTURE BAI ODYSSEY AUV LATCH			
	FINISH AS NOTED			B latch5cb 156-97-007			
				SCALE NONE RELEASE DATE SHEET OF	_		

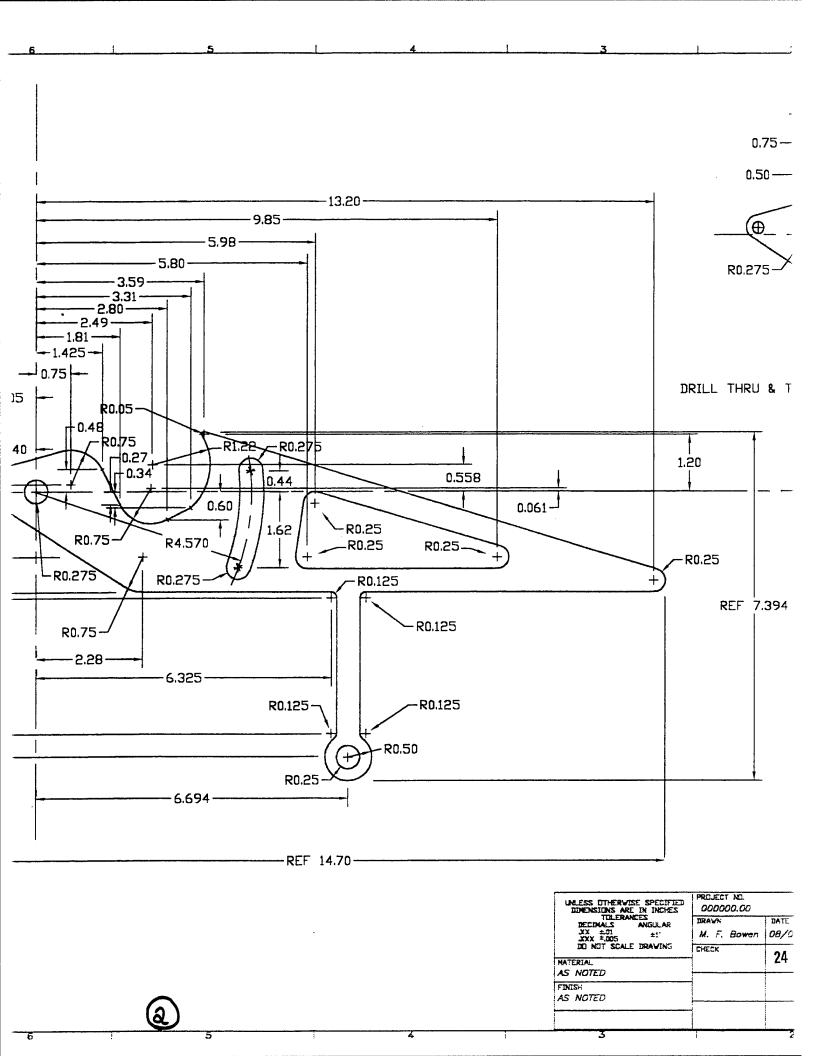
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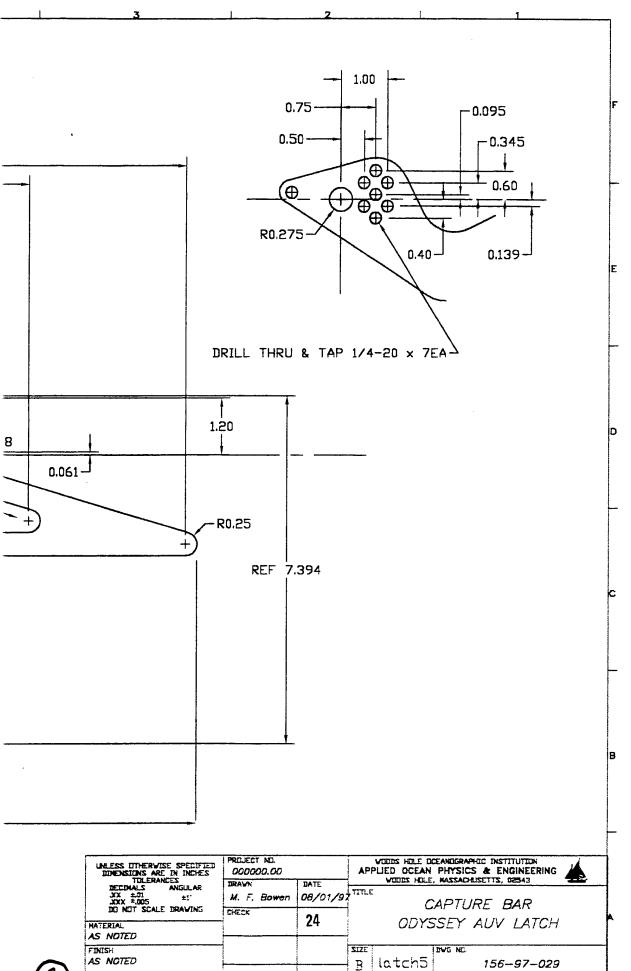
-12.653-12.420-R0.25 6.52--3.93--R0.125 R0.75-CUTDUT 10,43 9.66 LDRILLETAP 1/4 7.22 RO. 6.43 4,41 **(**) NOTES: BREAK ALL SHARP EDGES BILATERALLY SYMETRICAL ALL HOLES BRILL THRU MATERIAL: 6AL-4V TITANIUM PLATE, 3/8' **-3.76**7-







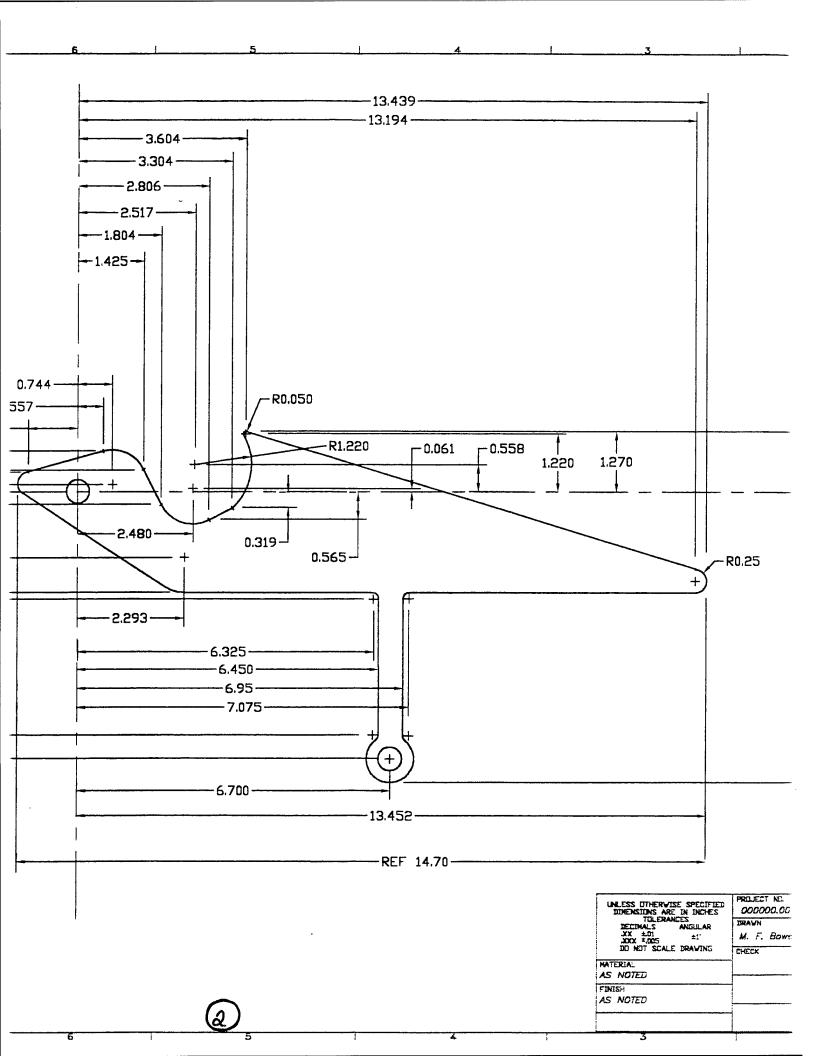


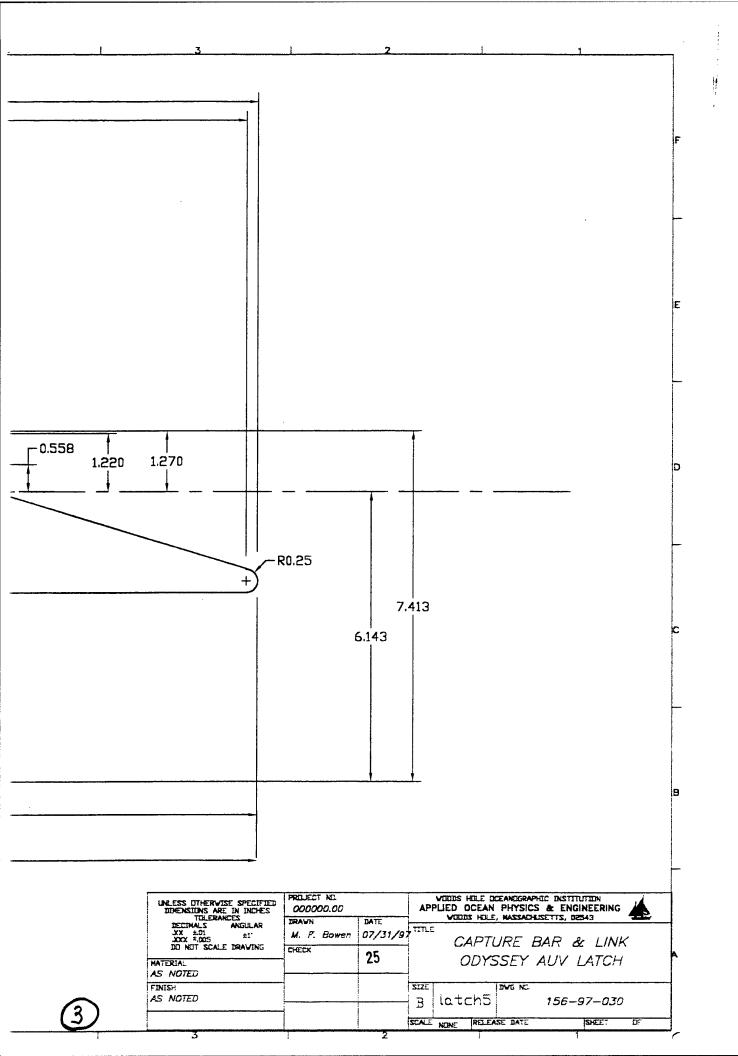


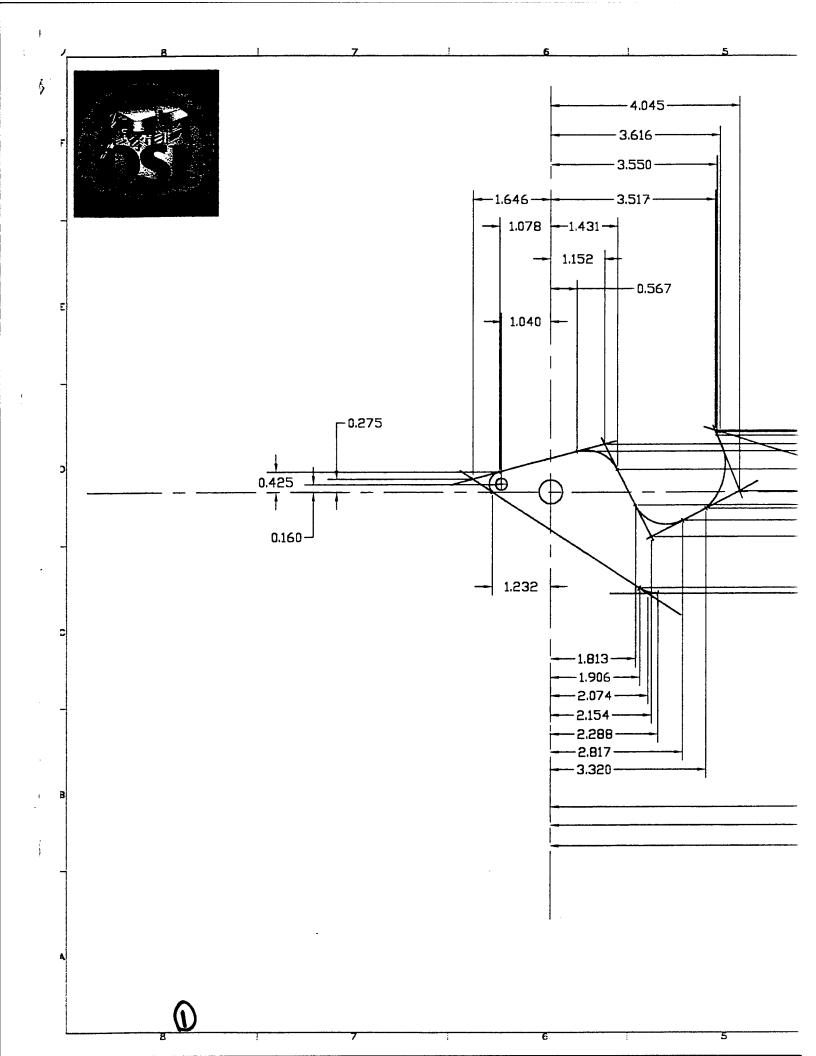
SCALE NUNE RELEASE DATE

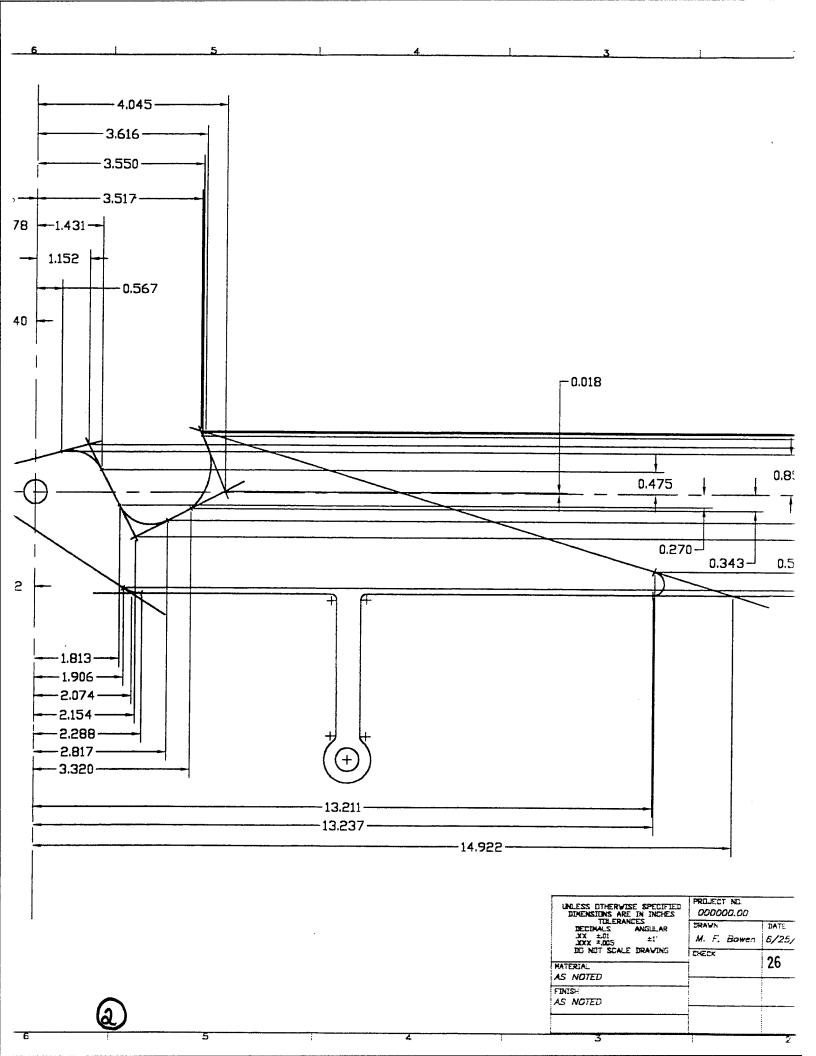
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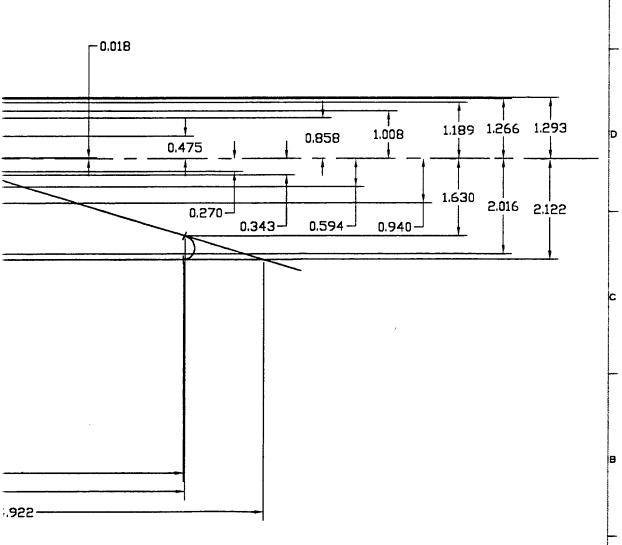
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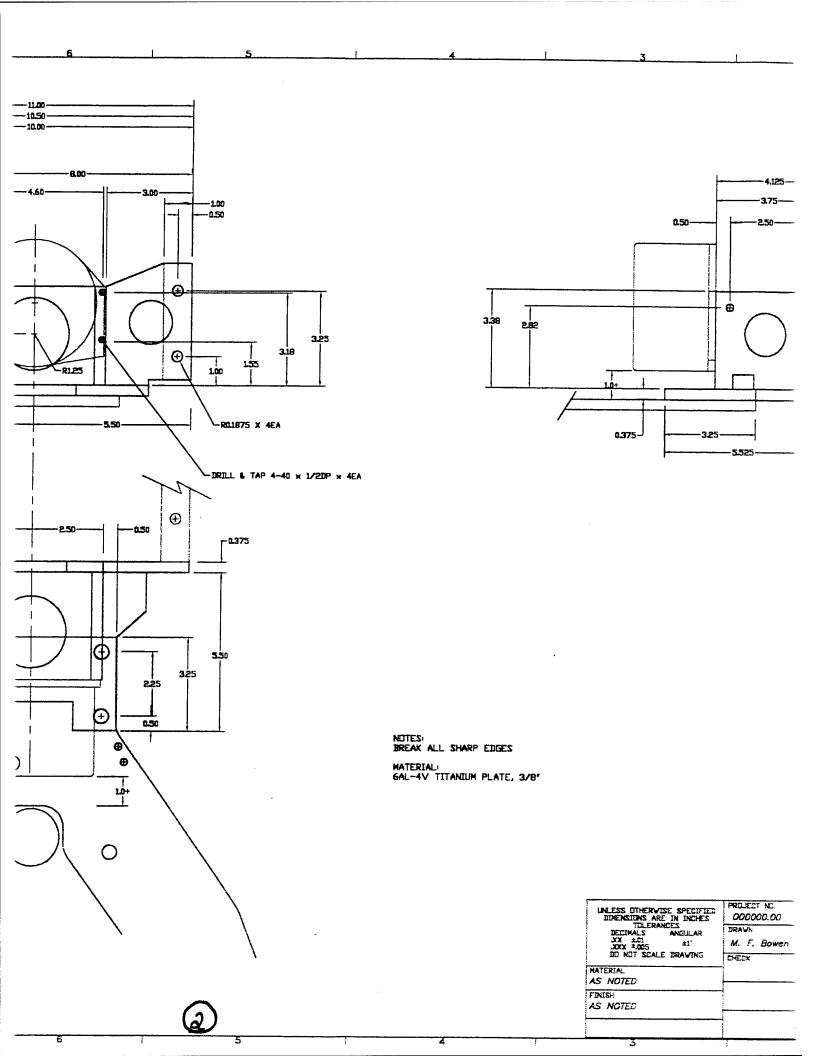






VOUDS HOLE DEEANGRAPHIC INSTITUTION
APPLIED OCEAN PHYSICS & ENGINEERING
VOUDS HOLE, MASSACHUSETTS, 02543 PROJECT NO. UNLESS DTHERWISE SPECIFIED
DIMENSIONS ARE IN INCHES
TILLERANCES
DECIDALS ANGULAR
JIX ±01 ±1'
JIXX ±005
DEI NUT SCALE DRAVING 000000.00 DRAWN 6/25/97 M. F. Bowen CAPTURE BAR, BY CONRADS CHECK 26 ODYSSEY AUV LATCH MATERIAL AS NOTED ZIZE IDVE NO FINISH AS NOTED В 156-97-022 SCALE NONE RELEASE DATE SHEET

(3)



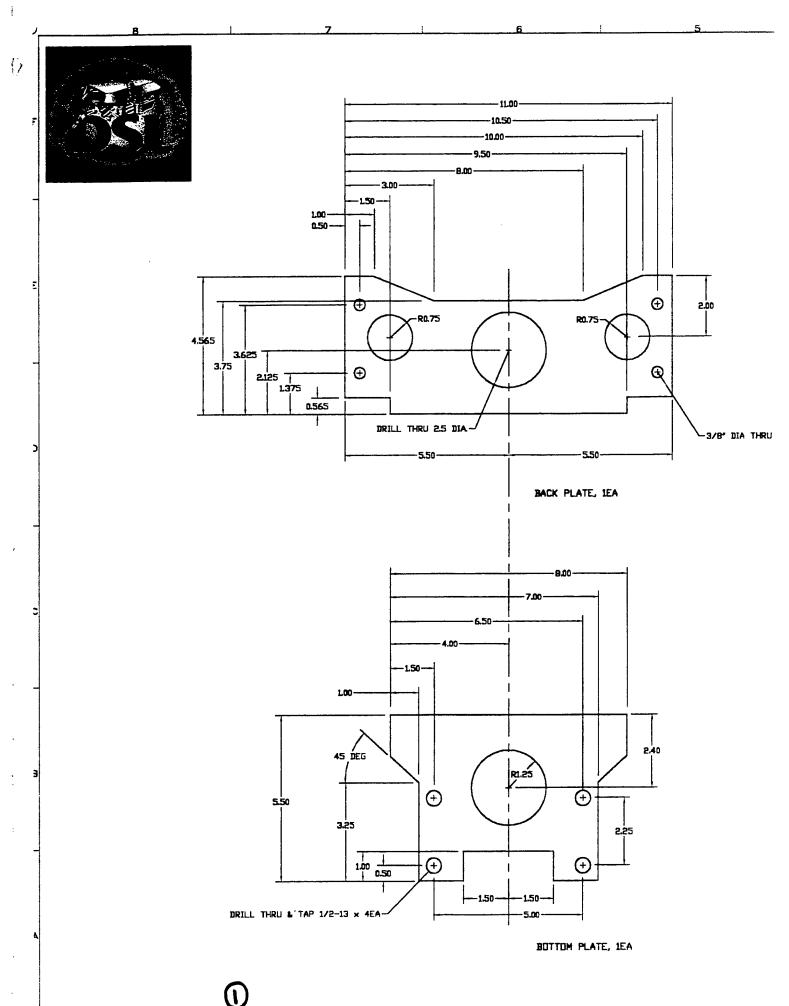
4.125 0.50-₿ 283 -DRILL THRU/% TAP 1/4-20 x 2EA 0.375 325 -0.375

SHARP EDGES

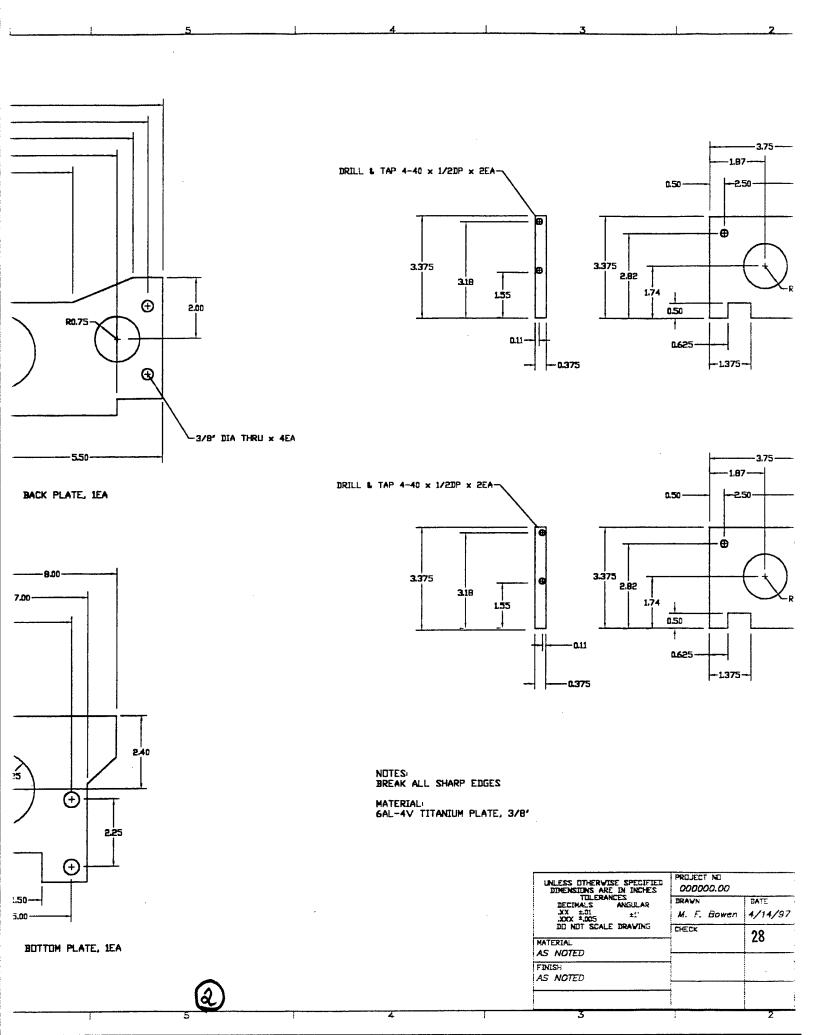
ANIUM PLATE, 3/8"

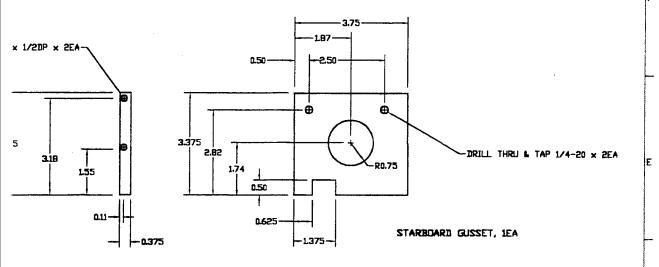
PROJECT NO. VEEDS HOLE DEEANDGRAPHIC INSTITUTION
APPLIED OCEAN PHYSICS & ENGINEERING
VEEDS HOLE, NASSACHUSETTS, 08343 UNLESS DIHERWISE SPECIFIED
DIMENSIONS ARE IN INCHES
TOLERALES ANGULAR
JAX ±01 ±1'
JAX ±01 51'
JAX ±01 ANGULAR
JAX ±01 ANGULAR 000000.00 DRAWN DATE M. F. Bowen 3/29/97 MOUNT ASSY, LATCH & USBL CHECK 27 ODYSSEY AUV LATCH MATERIAL AS NOTED FINISH SIZE DVS NO. AS NOTED 156-97-0001 \mathbb{B} mount! SCALE NUNE RELEASE DATE

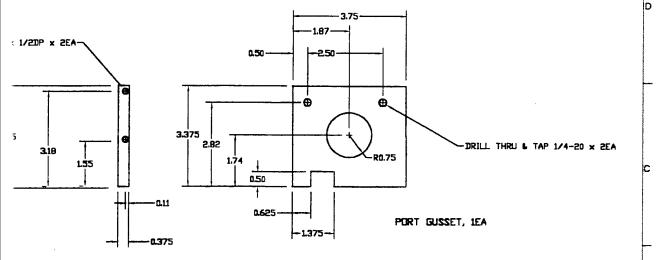
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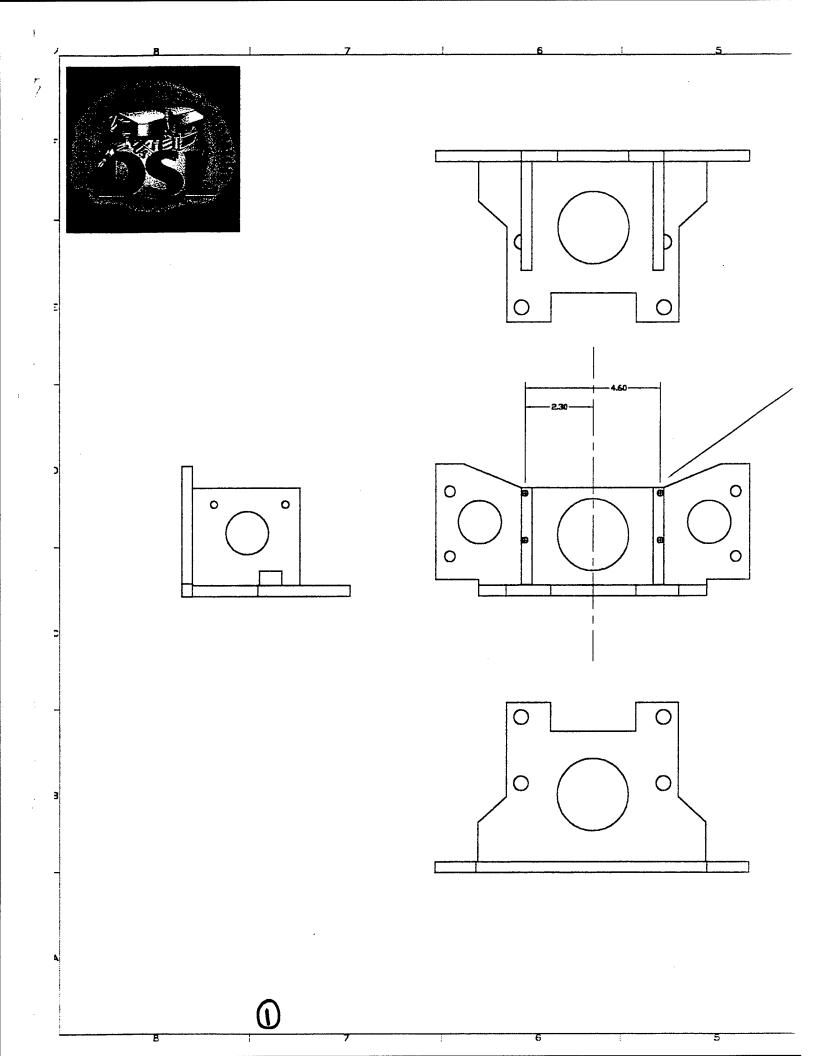


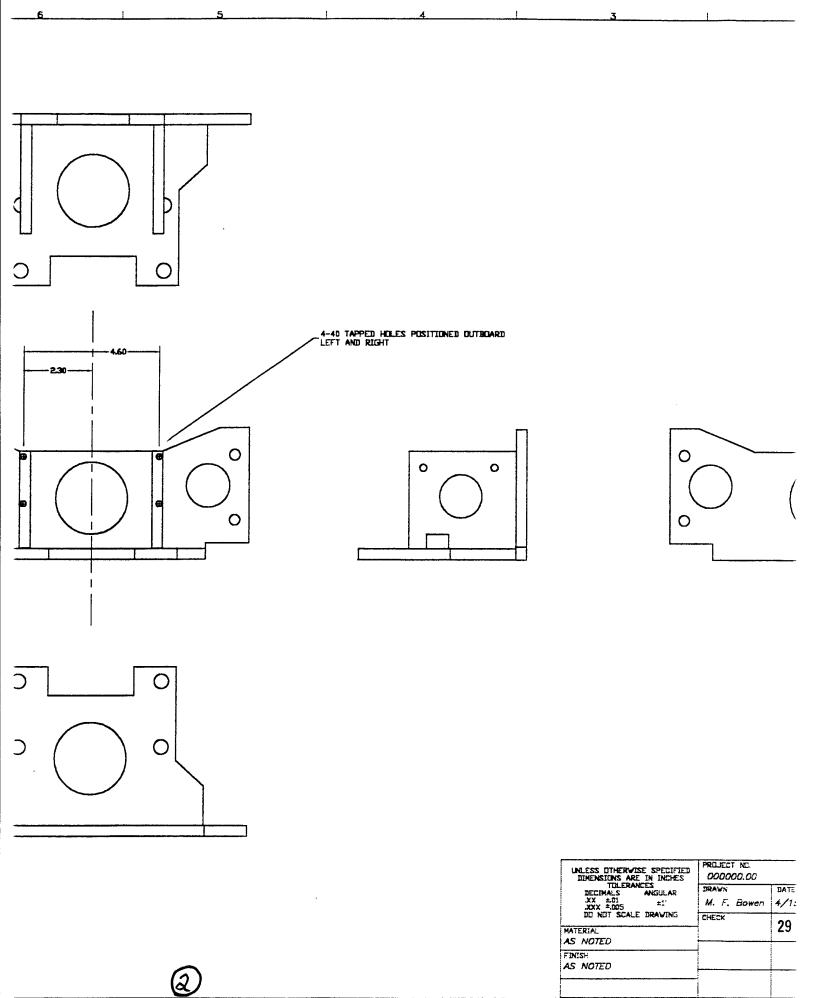


SHARP EDGES

TANIUM PLATE, 3/8'

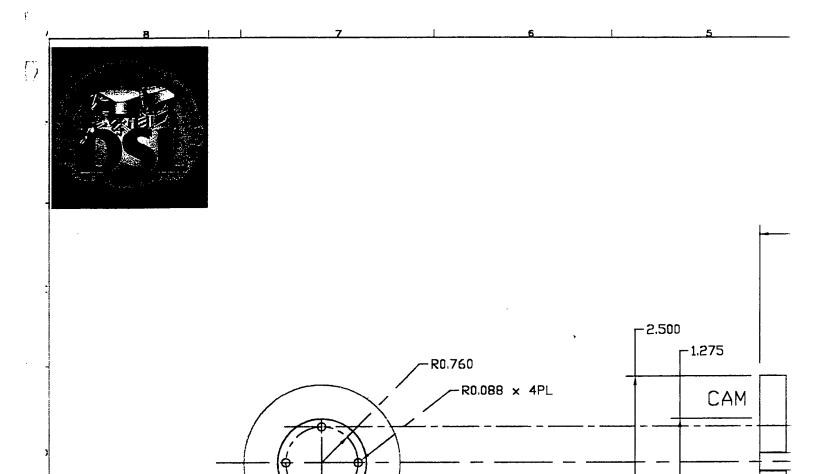
UNLESS DIHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TILLERANCES DECIMALS ANGULAR AXX ±.01 ±1' 20X ±.025	PROJECT NO 000000.00 DRAWN DATE 4/14/97		APPLIED OCEAN PHYSICS & ENGINEERING		4	
			TITLE DIMENSION, LATCH MOUNT			
DO NOT SCALE DRAVING MATERIAL AS NOTED	CHECK	28	ODYSSEY AUV LATCH			/
FINISH AS NOTED			size B	mountdin	156-97-008	
			SCALE	NONE RELE	EASE DATE SHEET D	<u>-</u>

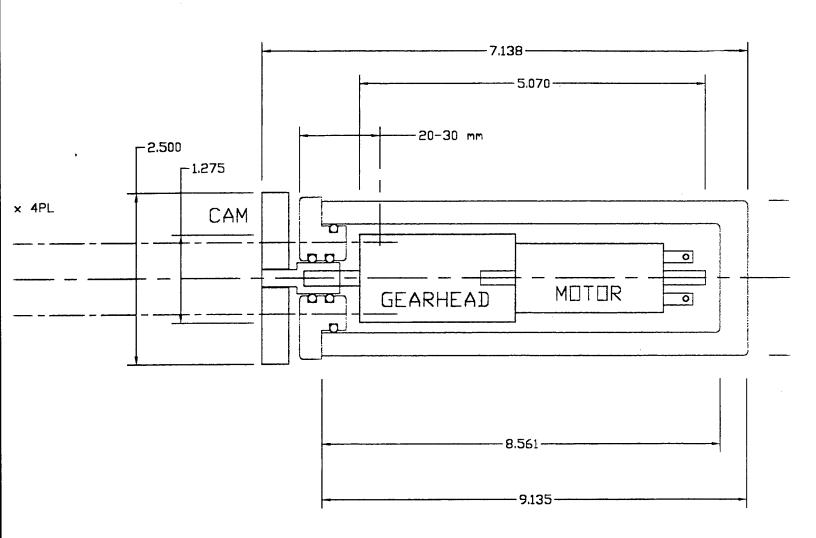


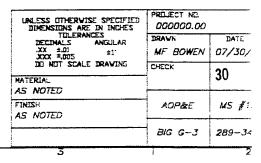


1 DUTBOARD 0 VIRIDS HELE DECANDISCAPHIC INSTITUTION
APPLIED OCEAN PHYSICS & ENGINEERING
VIRIDS HOLE, MASSACHUSETTS, 02543 PROJECT NO. UNLESS DIHERWISE SPECIFIED
DIMENSIONS ARE IN INCHES
TOLLERANCES
DECIMALS ANGULAR
XX ±01 ±1'
XXX ±005
DID NUT SCALE DRAWING 000000.00 DATE TITLE M. F. Bowen 4/15/97 MOUNT WELDMENT CHECK 29 MATERIAL AS NOTED ODYSSEY AUV LATCH FINISH SIZE DWG NE. AS NOTED В 156-97-009 weldnoun

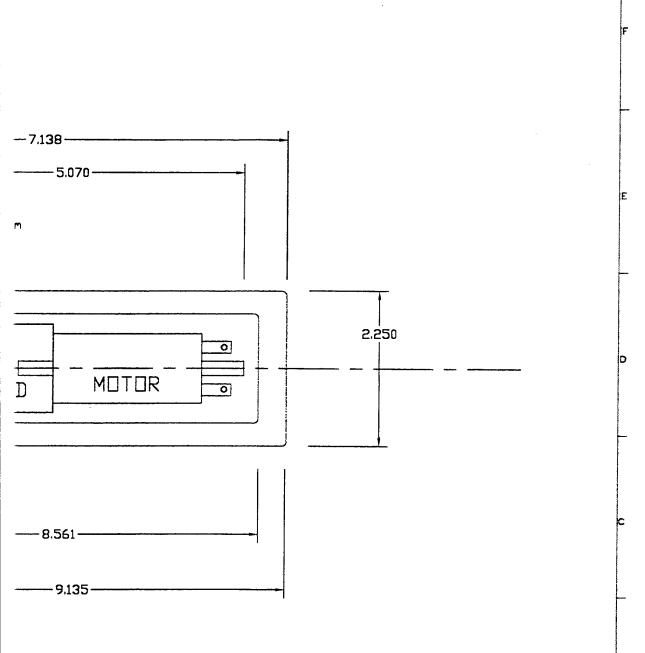
SCALE NUNE RELEASE DATE





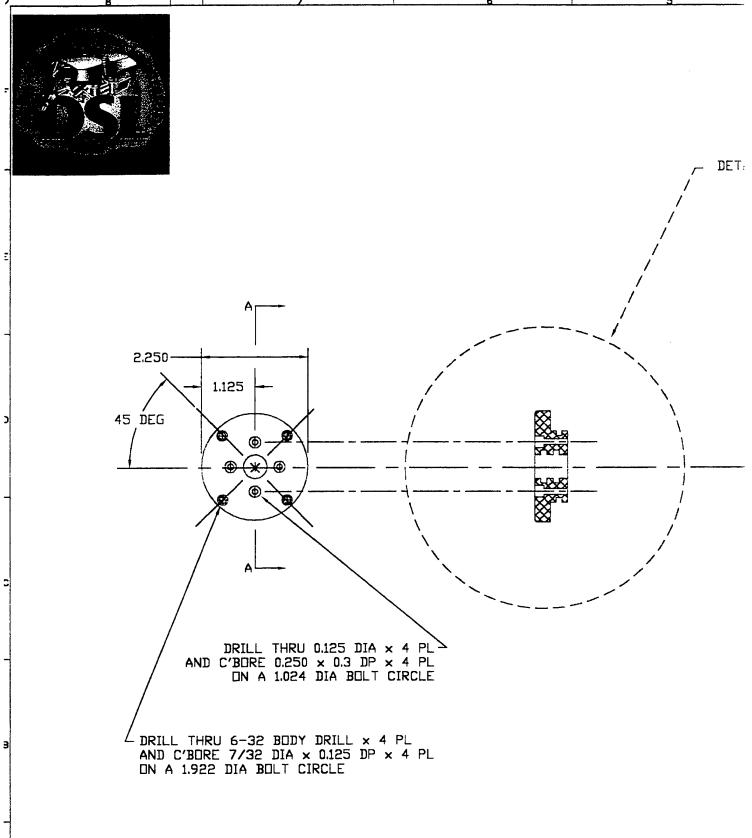






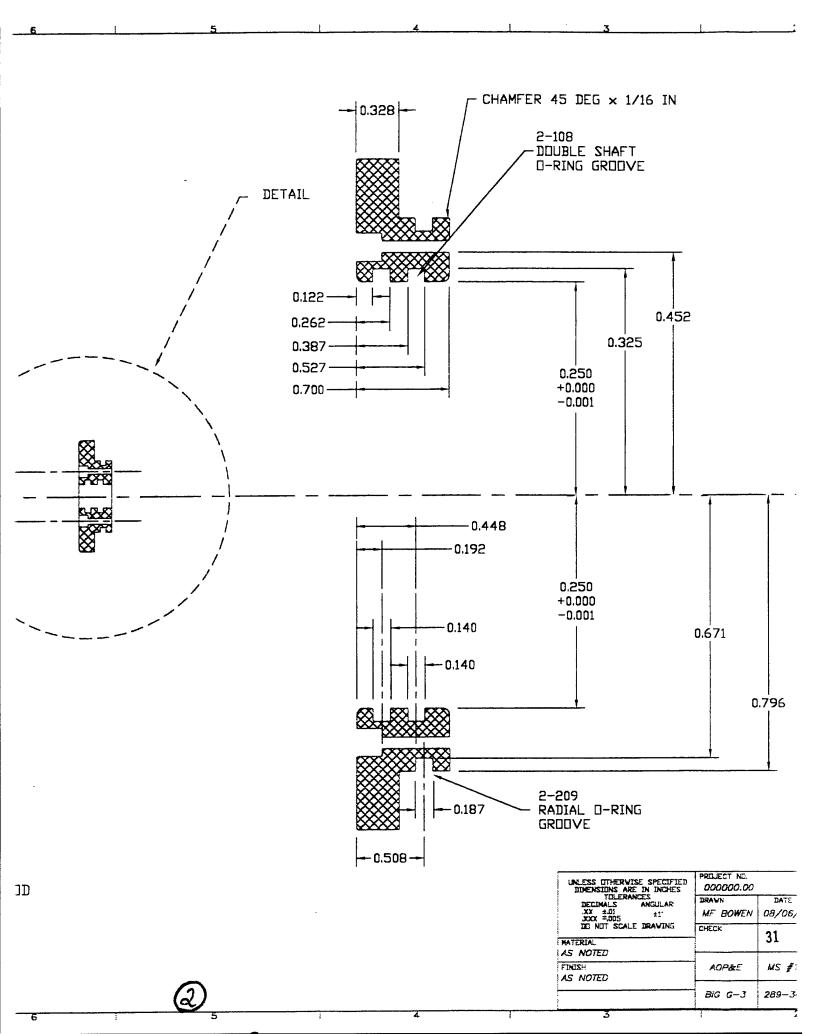
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	PRILJECT NO. 000000.00		VOLIDS HOLE DECAMBIGRAPHIC INSTITUTION APPLIED OCEAN PHYSICS & ENGINEERING	
TOLERANCES DECIMALS ANGULAR .XX ±.01 ±1 .XXX ±.005	MF BOWEN	DATE 07/30/97	TITLE ODYSSEY LATCH CAM	
ID NIT SCALE IRAVING MATERIAL AS NOTED	CHECK	30	MOTOR HOUSING OUTLINE	
FINISH AS NOTED	AOP&E	MS ∦ 13	SIZE DVG NC. 156—97—024	
	BIG G-3	289-3420	2	

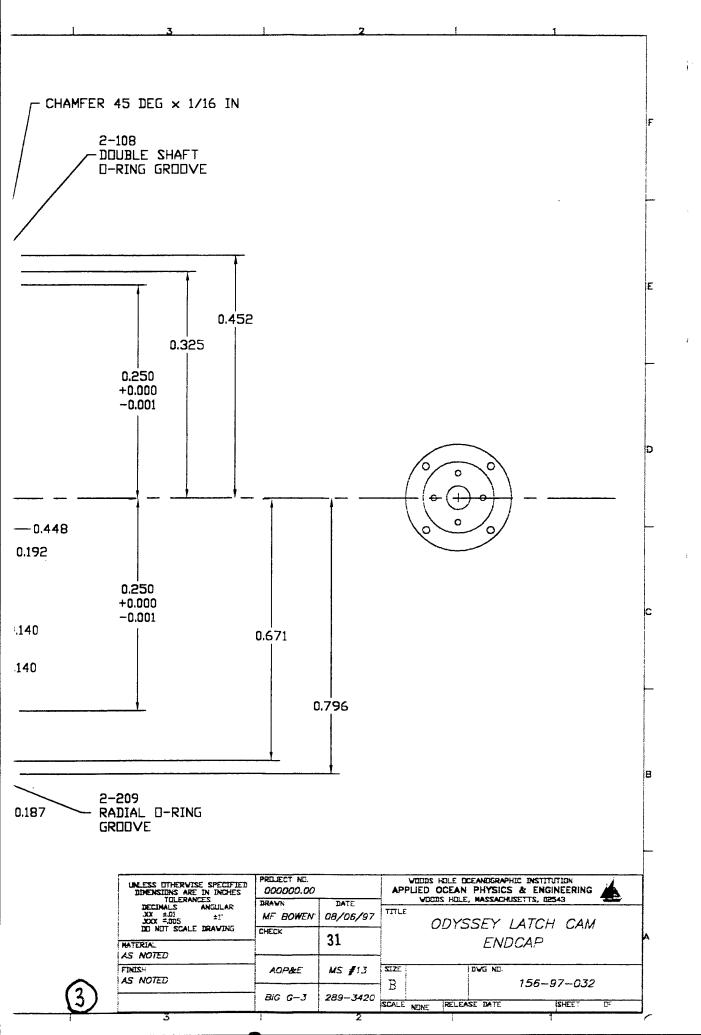
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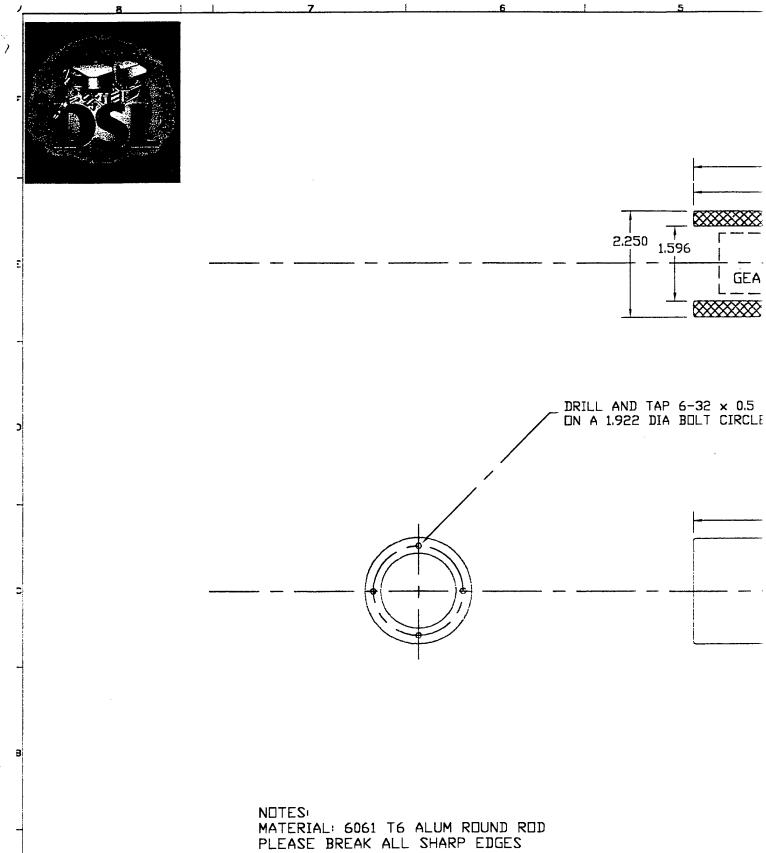


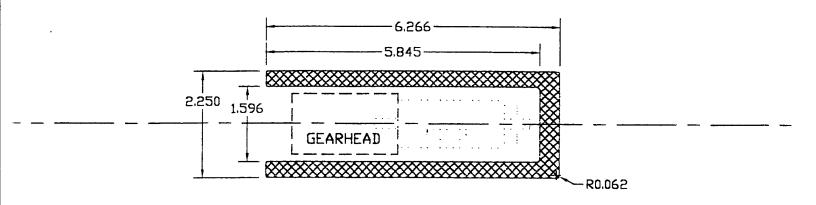
NOTES: MATERIAL: 6061 T6 ALUM ROUND ROD PLEASE BREAK ALL SHARP EDGES

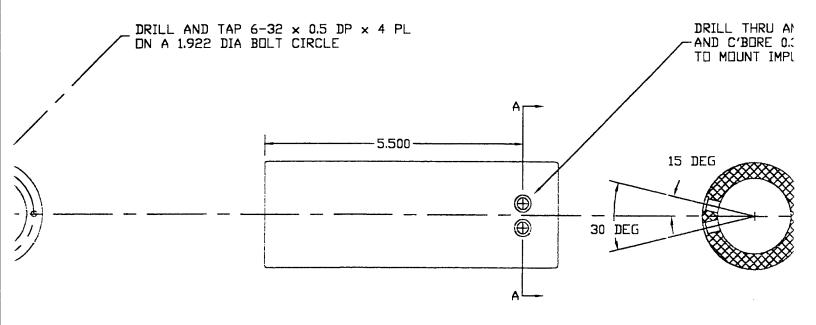
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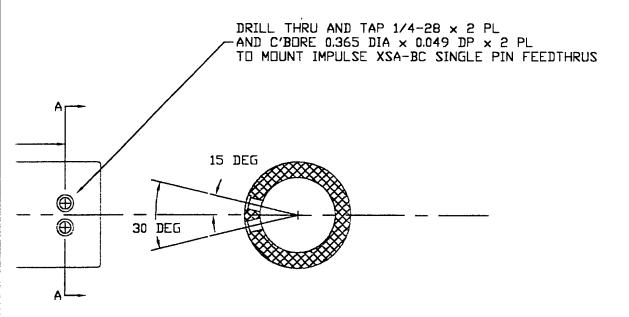


M ROUND ROD
ARP EDGES

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	000000.00	
TOLERANCES DECIMALS ANGULAR .XX ±DI .XXX ±DDS ±1: .XXX ±DDS DB NOT SCALE DRAVING	DRAWN MF BOWEN CHECK	
MATERIAL AS NOTED	-	
FINISH AS NOTED	AOP&E	
	BIG G-3	
3		

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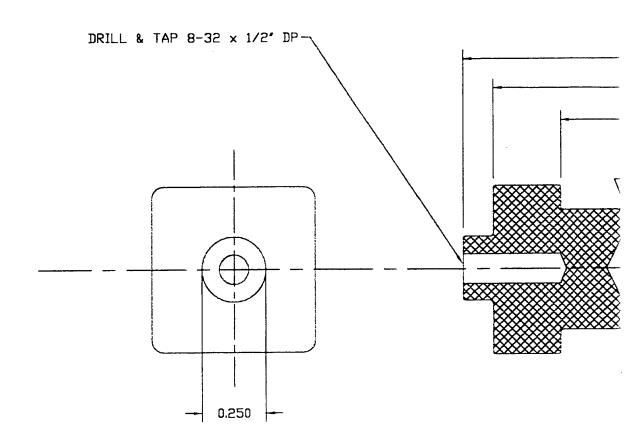




000000.00		APPLIED OCEAN PHYSICS & ENGINEERING		
MF BOWEN	DATE 08/06/97	TITLE	1	
SHECK 32		MOTOR HOUSING DETAIL	٨	
AOP&E	MS # 13	DVG NE. 156-07-033	1	
BIG G-3	289-3420	1 2	$\frac{1}{2}$	
	BRAVN MF BOWEN CHECK AOP&E	DRAWN DATE MF BOWEN 08/06/97 CHECK 32 AOP&E MS #13	DRAVN MF BOWEN 08/06/97 CHECK 32 ODYSSEY LATCH CAM MOTOR HOUSING DETAIL AOP&E MS \$13 BIG G-3 289-3420 DRAVN MOTOR HOUSING DETAIL 156-97-033	

(3



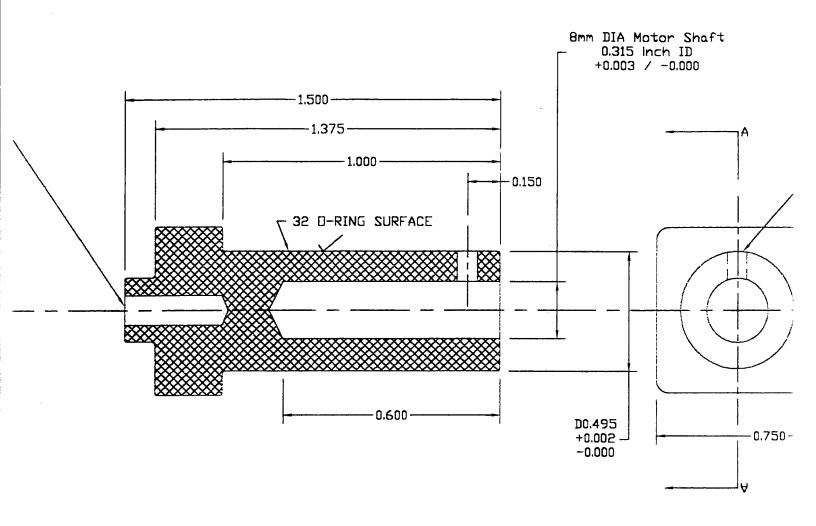


NDTES: MATERIAL: 316 STAINLESS STEEL PLEASE BREAK ALL SHARP EDGES

(1)

8

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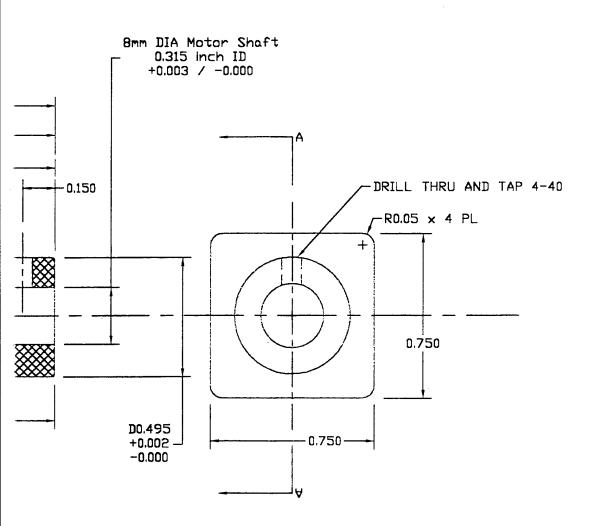


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UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	PRILJECT NO. 0000000.00		
TOLERANCES DECINALS ANGULAR .XX ±.01 .XXX ±.005	MF BOWEN	DATE 09/06/9	
DO NOT SCALE DRAWING	CHECK		
AS NOTED			
FINISH AS NOTED	AOP&E	MS ∦13	
	BIG G-3	289-341	
	' 		

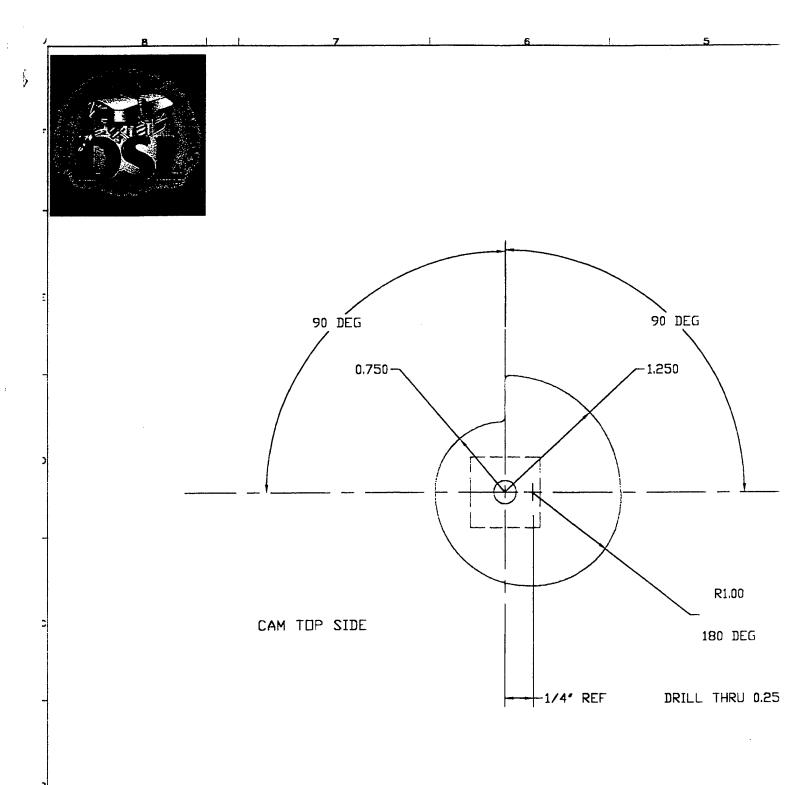
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UNLESS UTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	PRILECT NII. 000000.00		APPLIED OCEAN PHYSICS & ENGINEERING
TELERANCES DECIMALS ANGULAR .XX ±.01 ±1* .XXX ±.005	MF BOWEN	DATE 09/06/97	TITLE ODYSSEY LATCH CAM
DB NUT SCALE DRAVING HATERIAL AS NOTED	CHECK	3 3	CAM SHAFT DETAIL
FINISH AS NOTED	AOP&E	MS ∦ 13	SIZE DV6 NO. 1.56-97-0.34
	BIG G-3	289-3420	B 156-97-034 SCALE NONE RELEASE DATE SHEET OF

(3)



NOTES:
MATERIAL: DELRIN
PLEASE MAKE ARC TRANSITIONS AS SMOOTH AS POSSIBLE

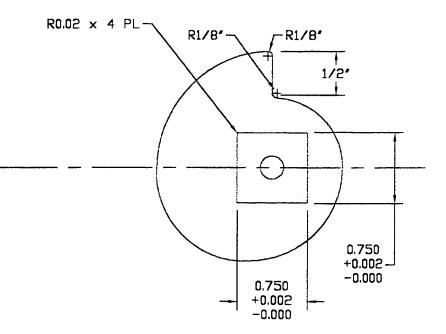
90 DEG 73/8' R0.02 x 4 PL R1/8'1,250
R1.00
180 DEG 7/4' REF DRILL THRU 0.250 DIA CAM MOTOR SIDE

ITIONS AS SMOOTH AS POSSIBLE

UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES TIBLERANCES DECIMALS ANGULAR .XX ±0.01 .XXX ±0.05 .ED NOT SCALE DRAVING MATERIAL	PRELIECT NG. 000000.00 BRAWN MF BOWEN C CHECK		
AS NOTED FINISH AS NOTED	AOP&E		
	BIG G-3	2	

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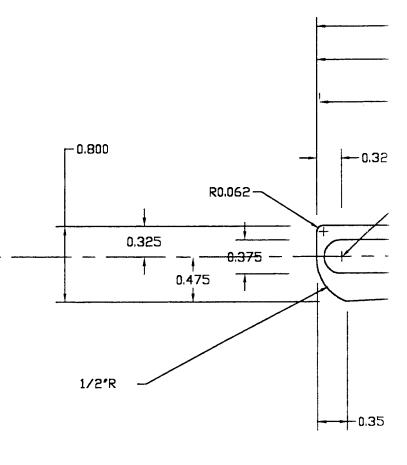
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CAM MOTOR SIDE

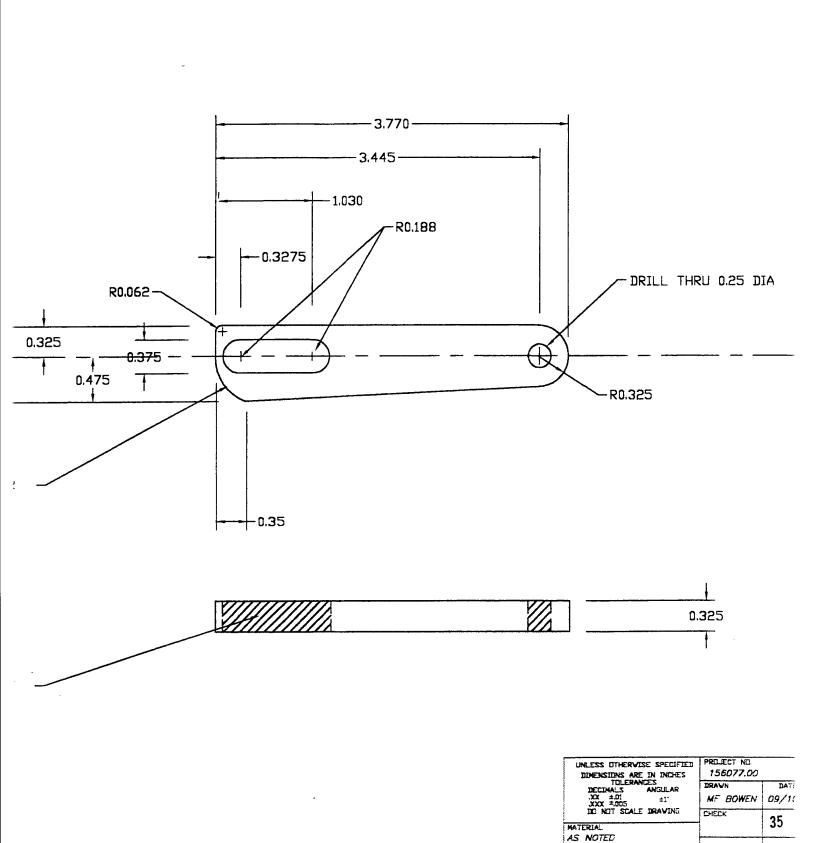
UNLESS OTHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	PRILECT NO. 000000.00		VIDIDS HOLE DECANDIGRAPHIC INSTITUTION APPLIED OCEAN PHYSICS & ENGINEERING		
TELERANCES DECIMALS ANGULAR XX ±.01 XXX ±.005	MF BOWEN	DATE 08/06/97	TITLE ODYSSEY LATCH CAM		
DE NOT SCALE DRAVING MATERIAL AS NOTED	CHECK	34	CAM DETAIL		
FINISH AS NOTED	AOP&E	MS # 13	SIZE INVG ND 156-97-035		
	BIG G-3	289-3420	SCALE NEINE RELEASE DATE SHEET DE		







NOTES:
MATERIAL IS GRADE 2 TITANIUM
PLEASE-BREAK ALL SHARP EDGES
2EA REQUIRED
MARTIN BOWEN x3420
DWG# 15697040.DWG



FINISH

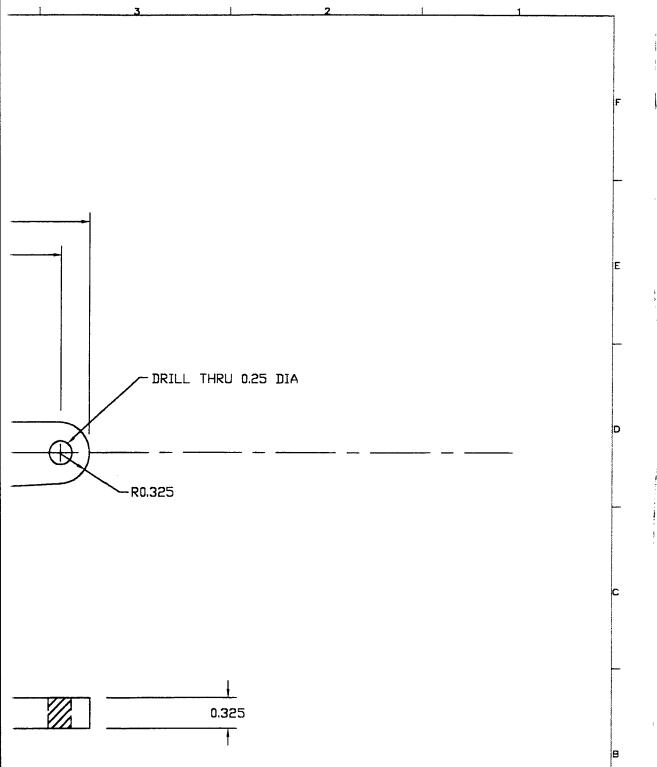
AS NOTED

AOP&E

BIG 402

M5 1

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UNLESS DIHERWISE SPECIFIED DIMENSIONS ARE IN INCHES	PRILECT NII. 156077.00		VOIDS HOLE DESANDGRAPHIC INSTITUTION APPLIED OCEAN PHYSICS & ENGINEERING		
TOLERANCES DECINALS ANGULAR .XX ±01 ±1: .XXX ±005	MF BOWEN	DATE 09/10/97	TITLE ODYSSEY LATCH CAM		
MATERIAL AS NOTED	CHECK	35	LATCH LINK		
FINISH AS NOTED	AOP&E	MS ∦ 9	SIZE DVG NO.		
	BIG 402	2 89- 3 420	SCALE NONE RELEASE DATE SHEET OF		

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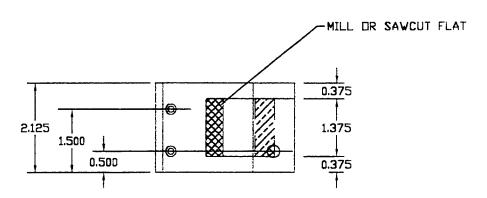


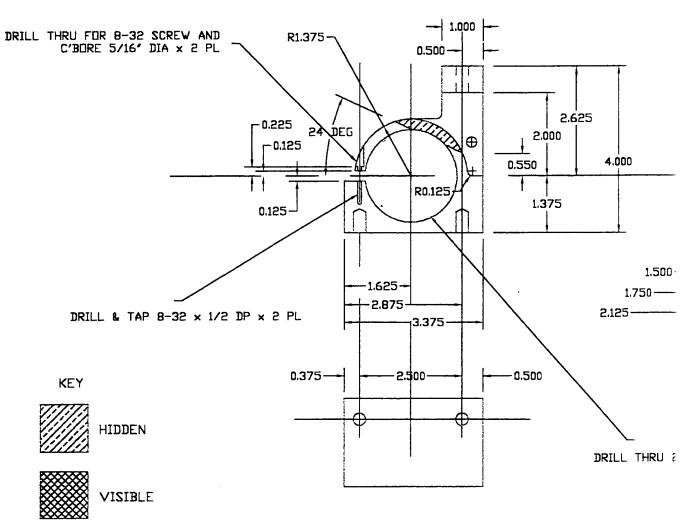
MARTIN F. BOWEN WHOI PHONE: 3420

ACCOUNT:

NO. REQUIRED: ___

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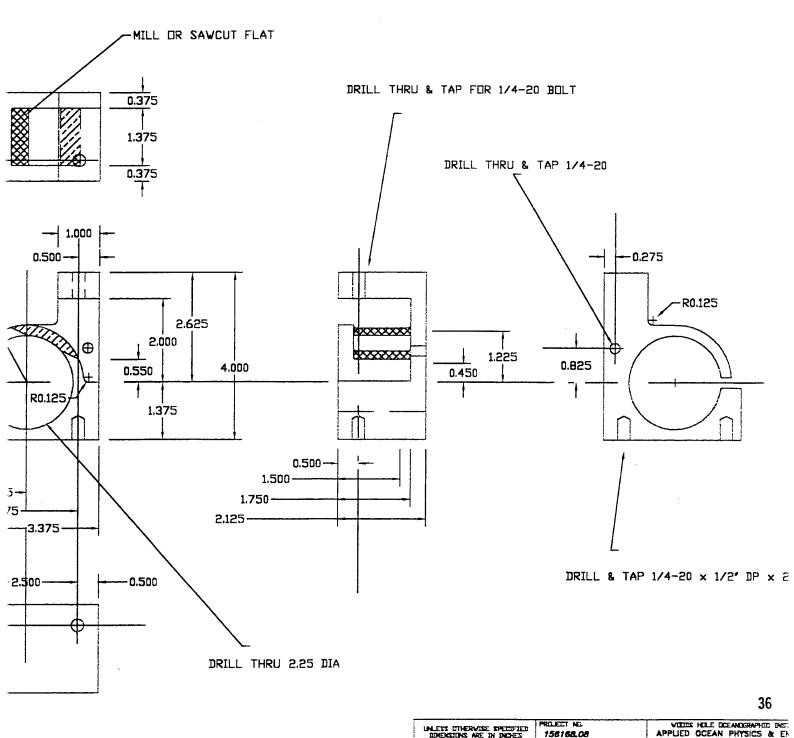




NOTES: BLACK OR WHITE DELRIN PLEASE BREAK ALL SHARP EDGES

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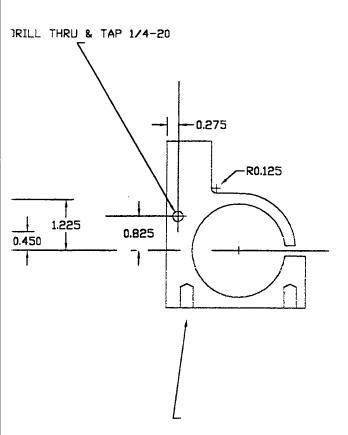


UNLESS OTHERVISE SPECIFIED DIDENSIONS ARE IN DICHES	156168.08		APPLIED OCEAN PHYSICS & EN		
THE FRANCES SECONDLS ANGLEAR JOX 2011 ±11 JOX 2005 ±01 DO NOT SCALE DRAWING MATERIA. AS NOTED	MF BOWEN	DATE 7 FEB 98	TITLE	MOTOR MO	
	CHECK	17 x 22	ODYSSEY AUV		
FINISH AS NOTED	AOP&E	us fs	SIZE	156 NO.	
	BIG 402	289-3420	SCALE NENE	RELEASE DATE	

JES



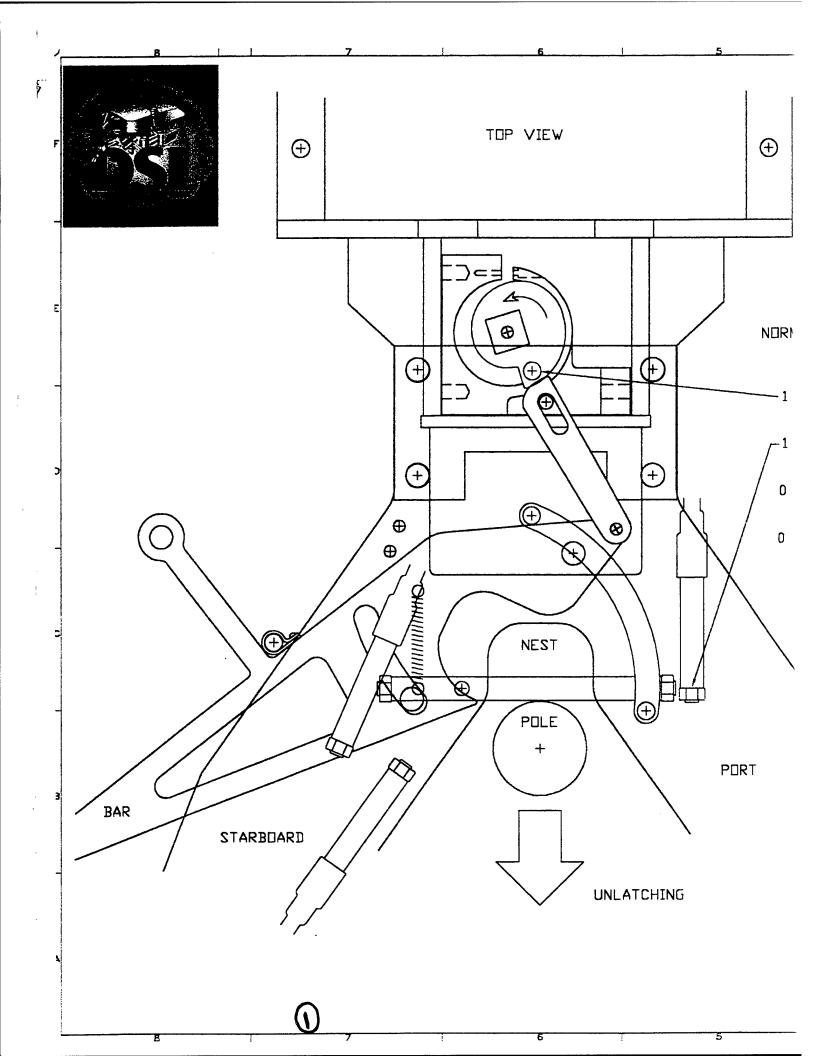
AP FOR 1/4-20 BOLT

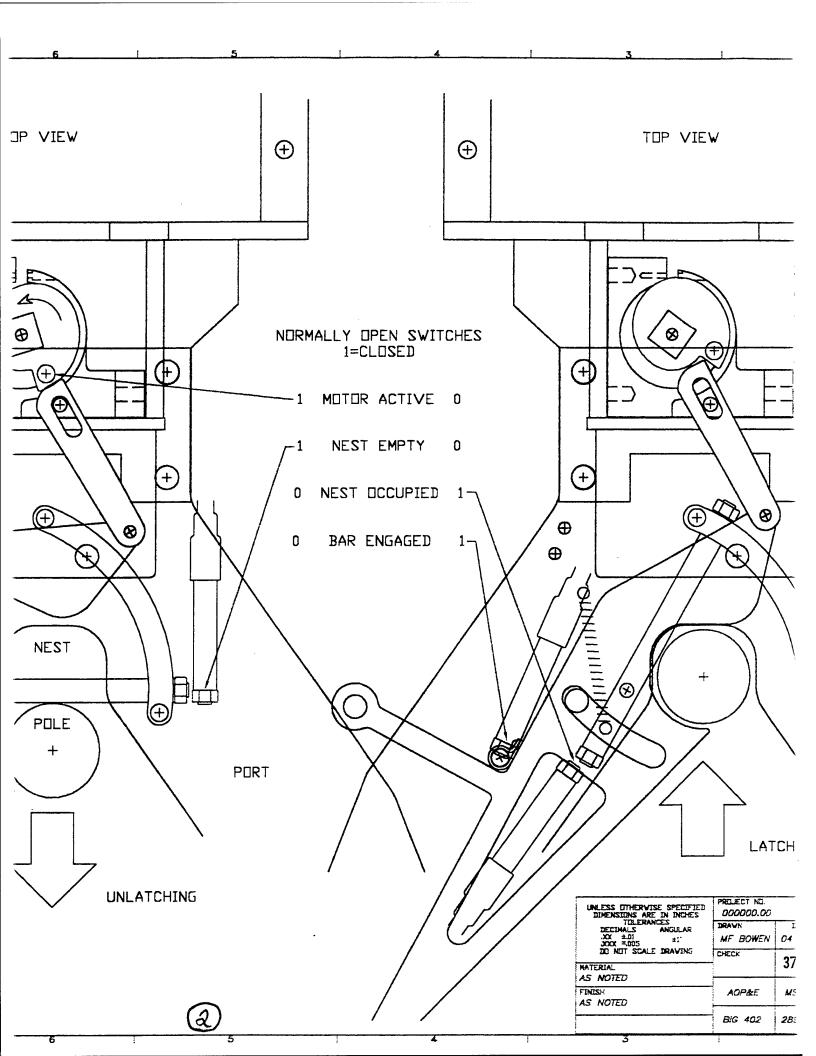


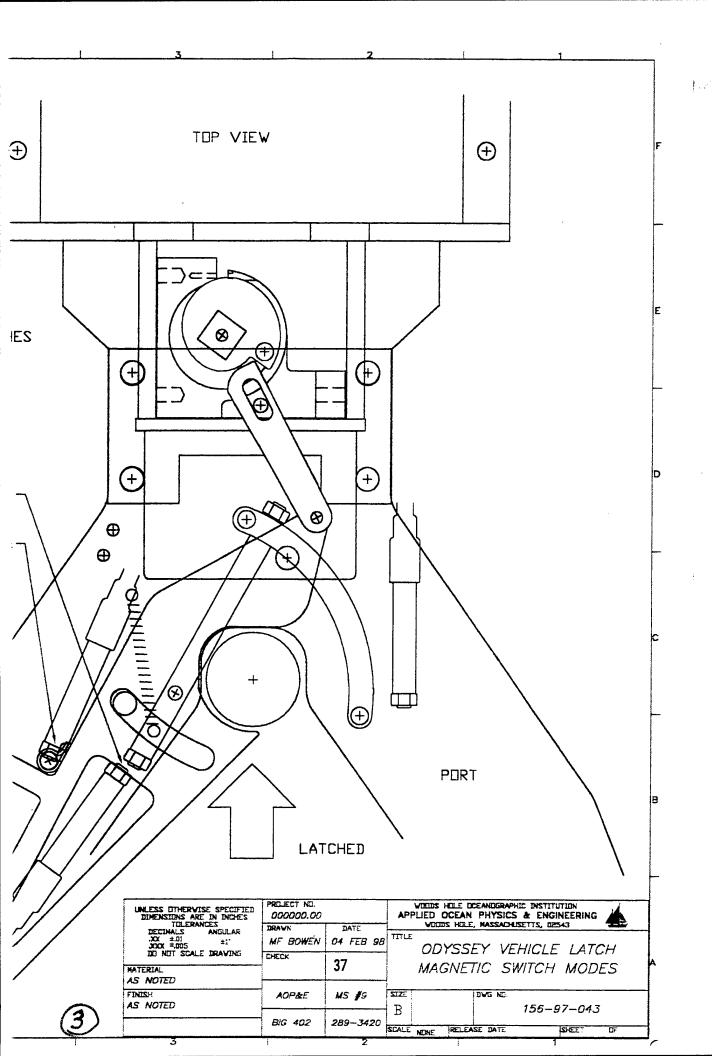
DRILL & TAP 1/4-20 x 1/2" DP x 2 PL

36

DTHERVISE SPECIFIED SIDNS ARE IN INCHES TILEPANCES	PRILECT NO. 156168.08		APPLIED OCEAN PHYSICS & ENGINEERING VUIDS HILE, MASSICHISETTS, 02543		
MALS ANGLAR	MF BOWEN	DATE 7 FEB 98	MOTOR MOUNT		
ET SCALE BRAVING CHECK		17 x 22	ODYSSEY AUV LATCH		
7D	AOPA E	NS #9	SIZE DVG MD. 156—98—041		
	BIG 402	289-3420	SEALE NEWF RELEASE DATE SHEET OF		







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			6.			
7. Author(s) M. F. Bowen				Organization Rept. No. I-98-12		
9. Performing Organization Name and	Address		10. Project/Tas	k/Work Unit No.		
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12. Sponsoring Organization Name and Office of Naval Research	d Address			oort & Period Covered nical Report		
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			14.			
15. Supplementary Notes This report should be cited	as: Woods Hole Oceanog. Inst. Tech.	Rept., WHOI-98-1	2			
16. Abstract (Limit: 200 words)						
device, shock-mounted to midwater docking station, docking pole. Latching to indication generated by pr station. Unlatching action The possibility of system normal unlatching behavior Two WHOI AUV latches	DDYSSEY-class autonomous underwate the bow of the AUV. When the AUV c the latch leads the AUV's approach an the pole is an entirely passive event requoximity switches mounted on the device requires one revolution of a latch motor malfunction was considered in latch desor, or the station fails, the latch defaults have been used successfully on three of	oncludes a survey of d is the first device quiring only forward e initiates AUV por cam and a brief begin. If for any reast by securing the A	mission and returns to collide with the dimotion of the AU wer and data trans acking command to the latched vehulv to the moored	s to a moored, le station's vertical ly. A positive capture fer servicing by the o the AUV thruster. licle cannot perform		
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